

Machine Learning techniques applied to FDM

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1. **Brief overview of Machine Learning**
2. First case study: Supervised Learning with TAP
3. Second case study: Unsupervised Learning with Sagem
4. Conclusions

Machine Learning (ML)

→ « development of algorithms which take **data as input** in order to **detect patterns, make predictions**, or more generally **gain insights** and knowledge about the mechanism generating the data ».

Machine Learning (ML)

- Recent field of study,
- Has seen tremendous development these recent years,
- Applied to many fields of application:
 - Computer Vision,
 - Finance,
 - Economy,
 - Biology,
 - Marketing.

Machine Learning (ML)

→ Essentially two types of Machine Learning:

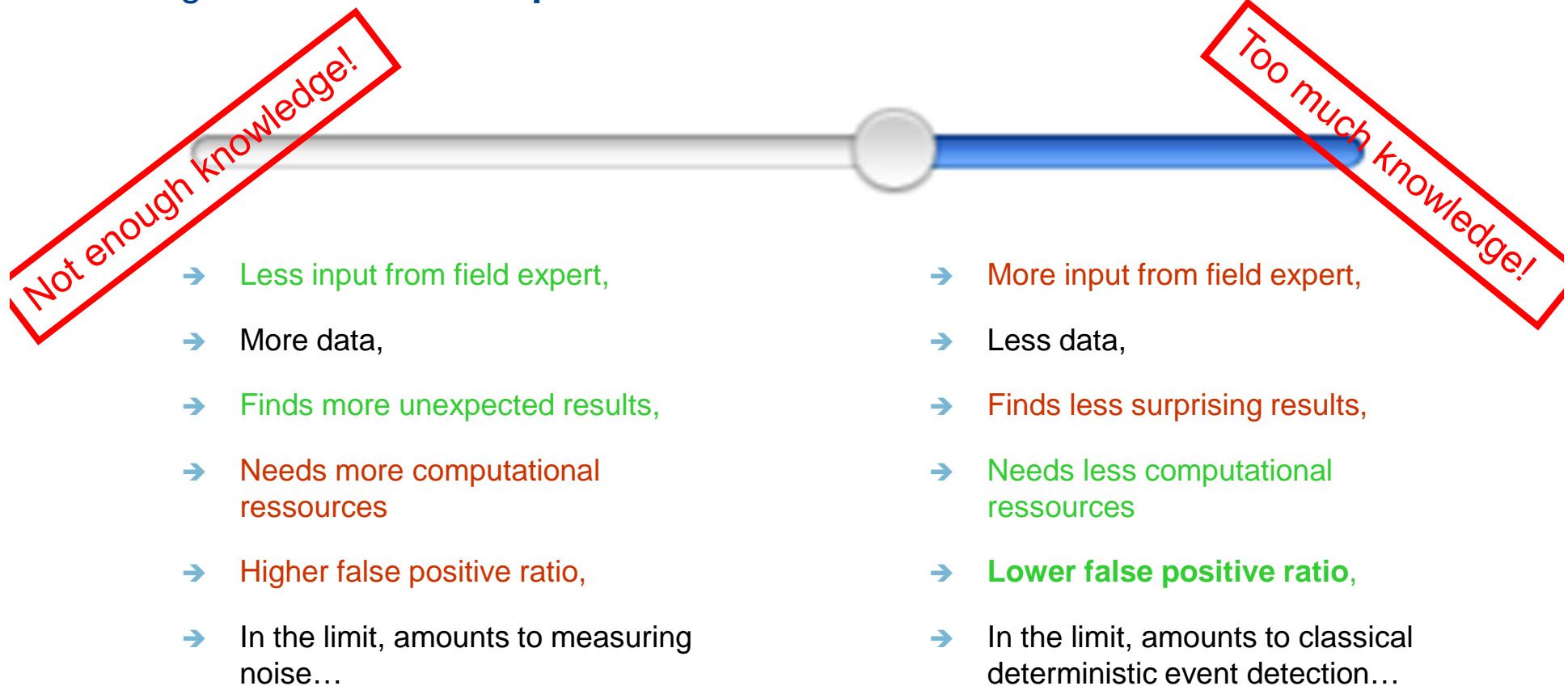
	SUPERVISED	UNSUPERVISED
Training phase?	YES	NO
Labeled data?	YES	NO
Goal	Make predictions	Discover structure

Added value of using Machine Learning for FDM?

1. Contrary to classical analysis, finds **unexpected** problems!
2. Extract more **value** from the data,
3. Gain **better understanding** of the mechanisms behind the data.

The No Free Lunch theorem

- You can't just throw all your data into a ML algorithm and expect it to give you **relevant** results...field experts must be involved.
- The goal is to find a **compromise**...



Machine Learning: good practices

→ Machine Learning is **teamwork**:

- One **Machine Learning practitioner**, with Maths/Computer Science background,
- One or more **Field Experts**, in this case pilots, flight data analysts and FDM experts.

→ The Machine Learning practitioner...

- Stands at the interface between field experts and mathematical methods,
- Has responsibility to provide insights to the field experts about
 - How algorithms work,
 - What they can do,
 - What they **can't** do
- Receive feedback from field experts to gain a good comprehension of the data.

→ A good way to develop algorithms is to work in an **iterative** way.

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Autoland Flight File Construction

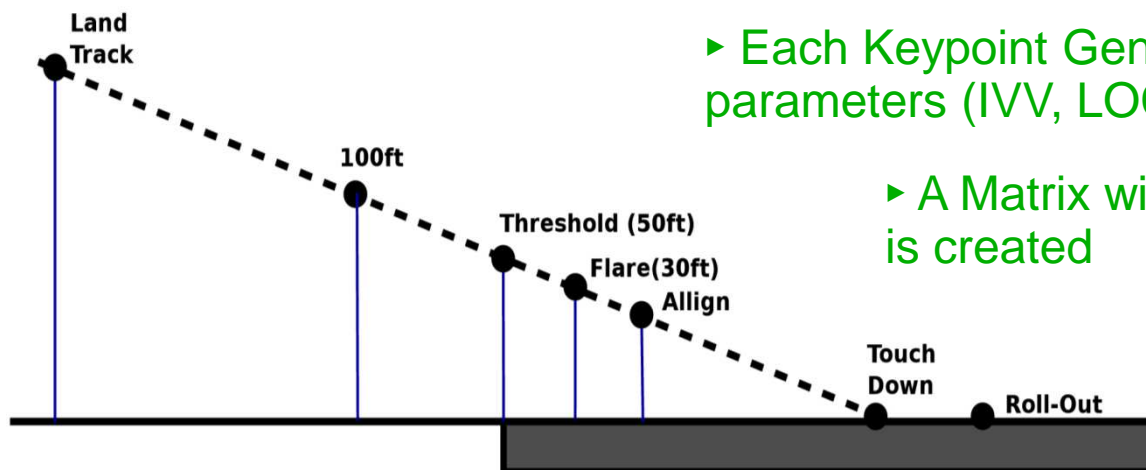


TAP PORTUGAL

► Procedure based on keypoints data extraction during landing

► Each Keypoint Generates around 30 snapshot parameters (IVV, LOCDEV, PITCH,VRTG, etc...)

► A Matrix with 279 dimensions per flight is created



(Sample)

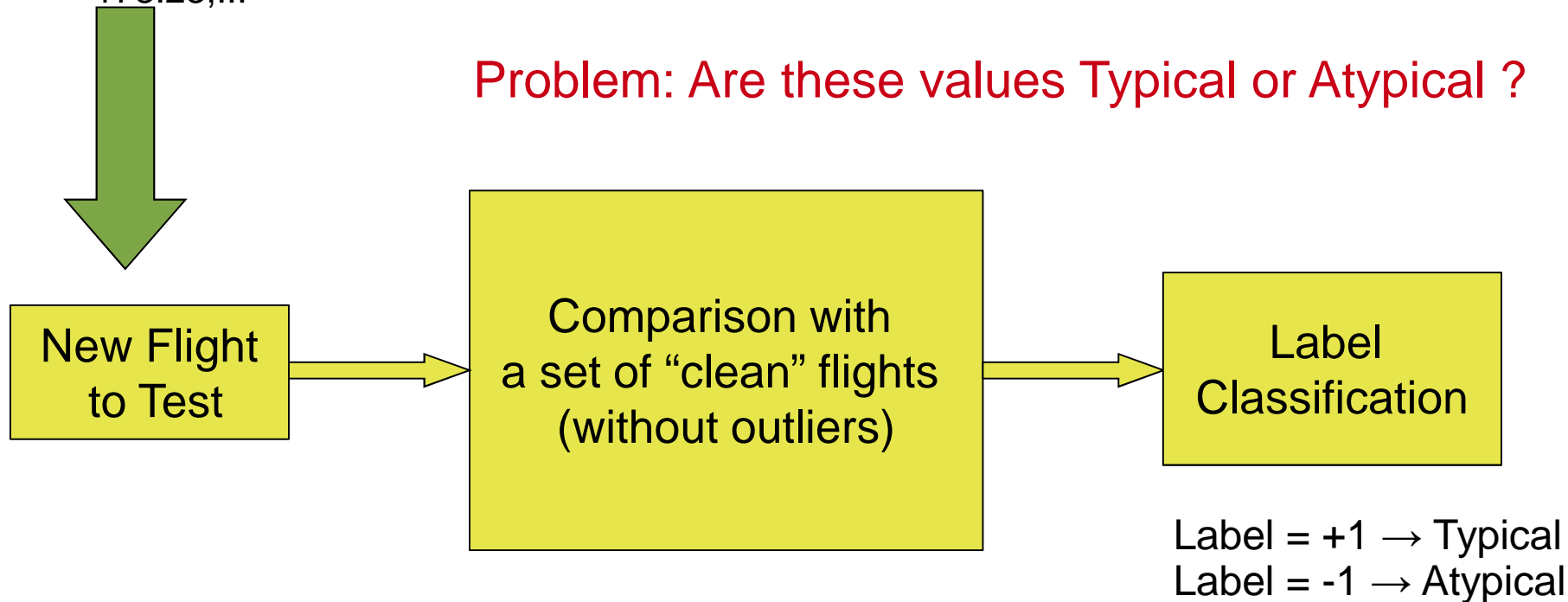
	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U	V	W	X	Y	Z
1	DESTINATION	RUNWAY_LD	DATE_TO	HEIGHTD	VAPR	ROD_LT	ROLL_LT	LOC1_LT	LOC2_LT	GS1_LT	GS2_LT	HDG_LT	PITCH_LT	IAS_LT	ALT_LT	TLA1_LT	TLA2_LT	N11_LT	N12_LT	N21_LT
2	LIS		21 11/02/2011	0	144.75	-12.8	0.35	1.56	0.98	5.86	5.08	205.05	2.46	143.25	524	3	3	62.38	62.5	88.88
3	ORY		6 16/02/2011	20	130.5	-12.27	1.41	-0.39	0	-8.98	-12.11	64.42	2.46	131.88	1156	3	3	46.5	46.38	82.13
4	MPX	35L	01/02/2011	0	139	-13.87	0.7	-1.37	-0.98	-1.95	-1.17	347.43	2.11	140.25	872	3	3	47.5	47.13	83.63
5	LIS		21 07/02/2011	0	125.25	-12.53	-0.35	1.17	0.98	-2.73	-3.52	206.19	2.46	125.38	364	3	3	47.5	47.38	84.75
6	ORY		6 16/02/2011	20	124.25	-11.73	-0.35	-0.59	-0.2	-13.67	-14.06	65.21	3.16	123.63	1144	3	3	46.25	46.88	82.75
7	HEL	04L	24/02/2011	134	126.25	-12.8	0	-1.17	-1.56	-11.33	-12.11	44.21	1.76	130.38	-96	3	3	44.13	44.13	80.75
8	BLQ		12 01/02/2011	0	125.5	-12.8	0	-0.59	-0.39	16.41	16.41	114.96	2.46	127.5	252	3	3	41.88	42.38	82
9	BLQ		12 01/02/2011	0	122	-11.47	0	0.39	0.39	3.91	3.91	114.79	2.81	122.88	292	3	3	44	43.88	82.5
10	VCE	04R	08/02/2011	0	121.5	-11.47	1.05	0	0.39	5.08	5.08	39.02	1.41	127.63	180	3	3	44.25	43.88	82.13
11	MUC	08L	09/02/2011	0	124	-10.93	0.7	0.39	0.78	-2.73	-3.13	81.91	2.46	125.88	1624	3	3	49.63	48.63	82.75
12	LIS		21 11/02/2011	0	124	-10.67	-0.35	-0.59	-0.59	-3.13	-3.52	204.79	2.81	122.88	552	3	3	54.5	55.13	87
13	LOPO		17 12/02/2011	108	130	-10.67	-0.7	-0.2	-0.2	-2.34	-3.13	171.04	2.11	130.13	236	3	3	49.5	49.63	84.25

New Flight Classification

NEW Autoland Flight Values created:

TJF,321,1988,LIS,03,OPO,17,20/08/12,108,130.00,-10.93,0.00,-0.78,-0.39,3.52,5.08,
173.23,...

Problem: Are these values Typical or Atypical ?



Input Space classification procedure

- ▶ Creation of a dataset without outliers (clean all cases with values over $\pm 3 \sigma$) = Training Dataset

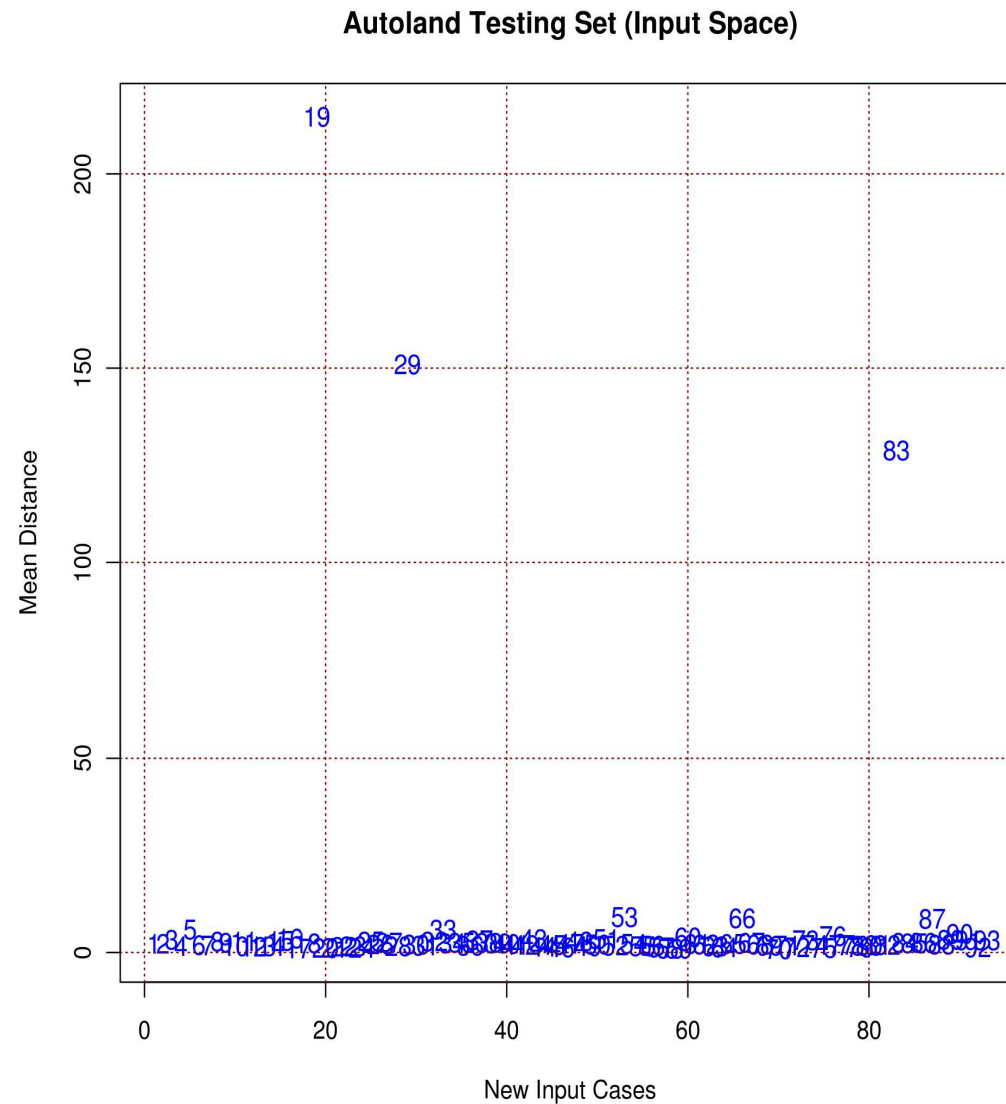
- ▶ Determination of the average (μ) and Standard deviation (σ) of each dimension (spreadsheet column) of the Training Dataset

- ▶ Each new value is Normalised \rightarrow remove the average and the scaling of each parameter
$$z_i = \frac{x_i - \mu}{\sigma}$$

- ▶ Calculation of the average distance
$$d_{med} = \sqrt{\frac{1}{m} \sum_{i=1}^m z_i^2}$$

- ▶ Each flight produces one average distance, which is plotted for a fast comparison of several flights....

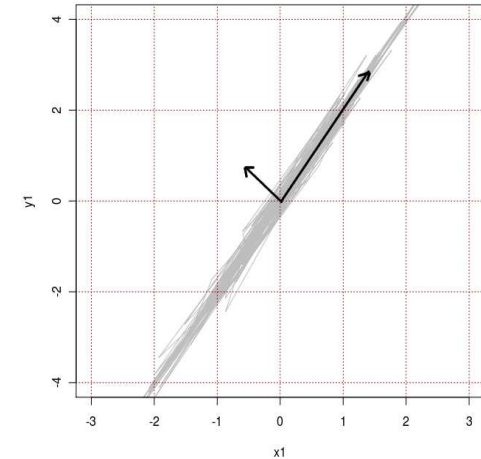
Average distances for 93 new flights (Input Space)



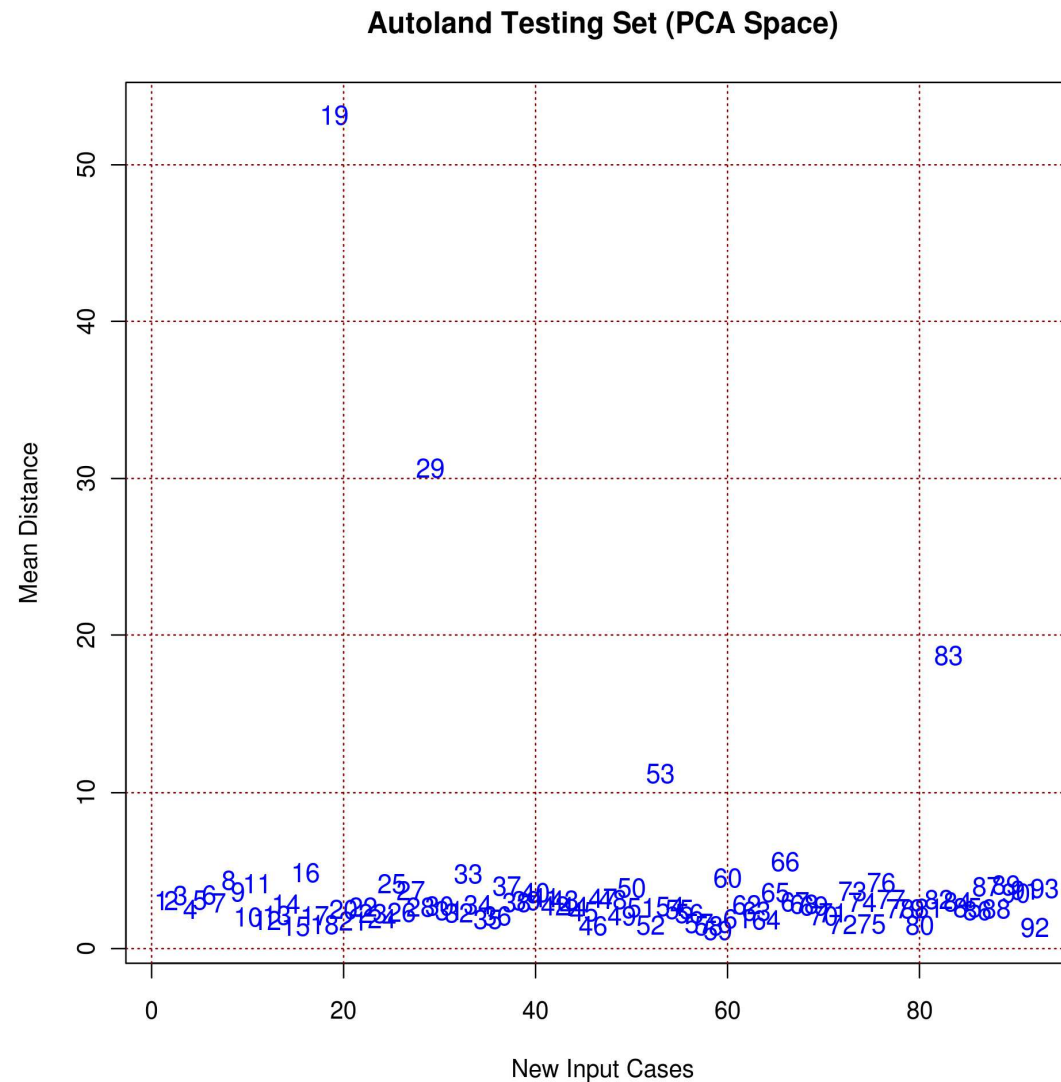
Another Perspective of the data

PCA – Principal Component Analysis

- ▶ Decomposition of the Data Matrix by its most important directions (Principal Components).
- ▶ Each new dimension is obtained by a Linear Combination of the original dimensions (ALT,CAS,PITCH,...).
- ▶ The new dimensions are ordered by decreasing order of variance and are uncorrelated with each other.
- ▶ A new flight is projected into the Principal Components space
- ▶ The Mean Distance is calculated as in the previous case.
- ▶ Plotting the Mean Distance for the same 93 flights using PCA....



Average distances for 93 new flights (PCA Space)



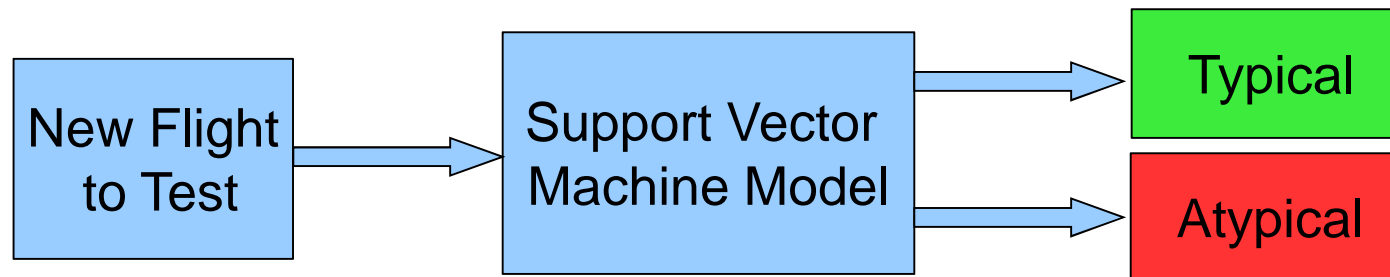
PCA and Input Space Summary



- ▶ Very useful for a fast evaluation of a set of flights
- ▶ Both methods apply to numerical values with Gaussian distributions
- ▶ Still there is data that cannot be tested with the two methods presented before:
 - Binary data (Landing Gear Squat Switches, Engine Valves, etc...)
 - Text data (Tail Number, Departure Airport, etc...)
 - Bit sequences (Autopilot Modes, etc...)
- ▶ New techniques based on “Statistical Learning Theory” can be used to overcome these limitations

Support Vector Machine (SVM)

- New approach for classification → Machine Learning Methods



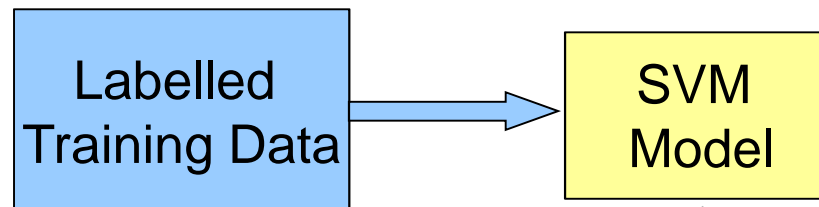
- Support Vector Machine – It's one algorithm that can “learn” from previous data generated and classify new inputs (flights)
- This algorithm is capable of dealing with binary and text data

SVM Model Construction

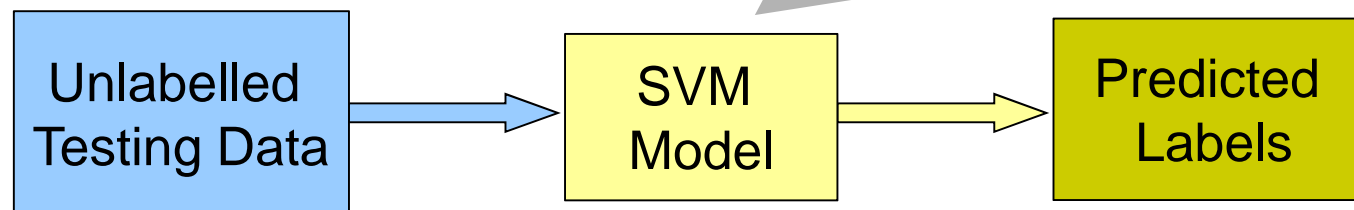
- The data structure is composed by data (x_{ij}) and its corresponding label (y_i)
- Supervised Learning Method → It relies on a Training Database with data and its corresponding known label

$$\begin{bmatrix} x_{11} & x_{12} & \dots & x_{1m} & , y_1 \\ x_{21} & x_{22} & \dots & x_{2m} & , y_2 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nm} & , y_n \end{bmatrix}$$

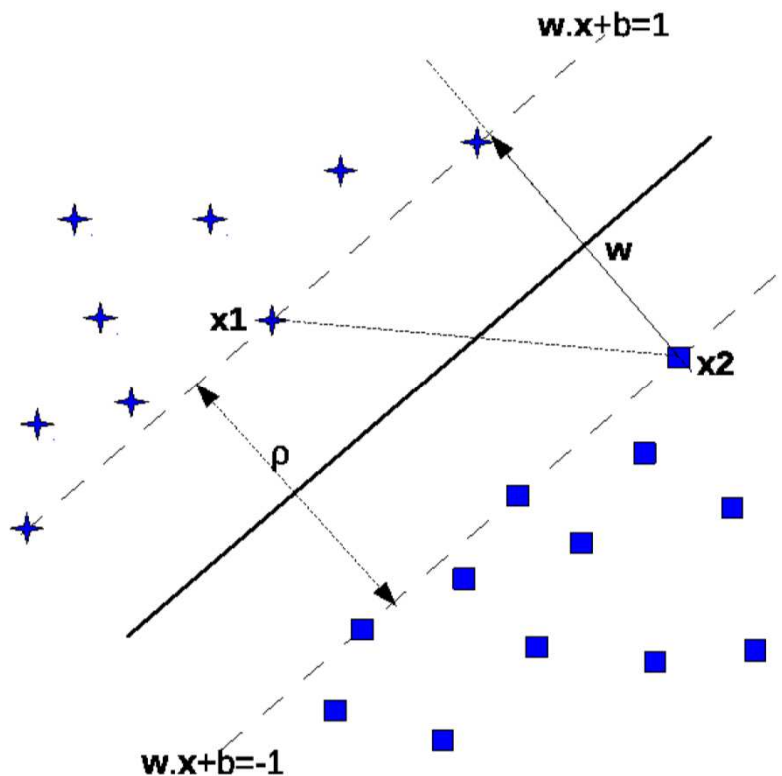
- Step #1 – Training Process



- Step #2 – Prediction for new inputs



The key ideas for SVM classification are:



►Determination of the best separation line between the two clusters of data

The best line is the one that maximizes the margin (ρ)

►The separation becomes possible using the vectors that lie on the lines...

$$w^T x_i + b = +1 \quad w^T x_i + b = -1$$

►... which are called the support vectors

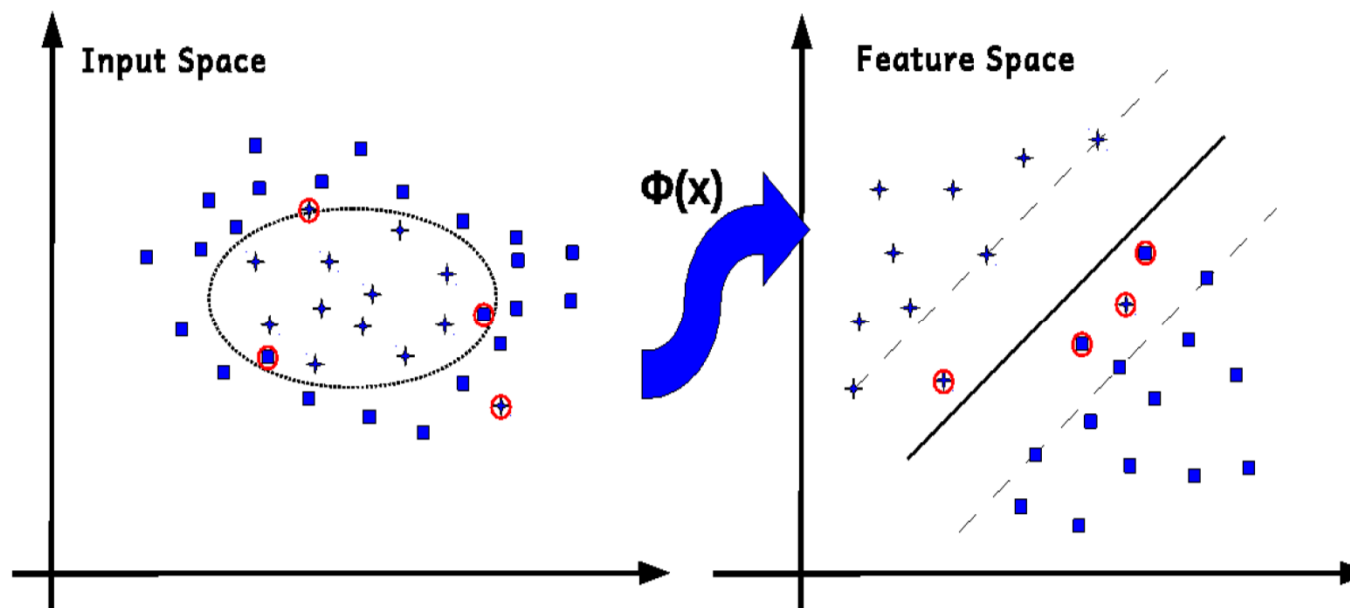
►Each new entry (x) is evaluated according to a decision function....

$$f(x) = \text{sign}(w^T x + b)$$

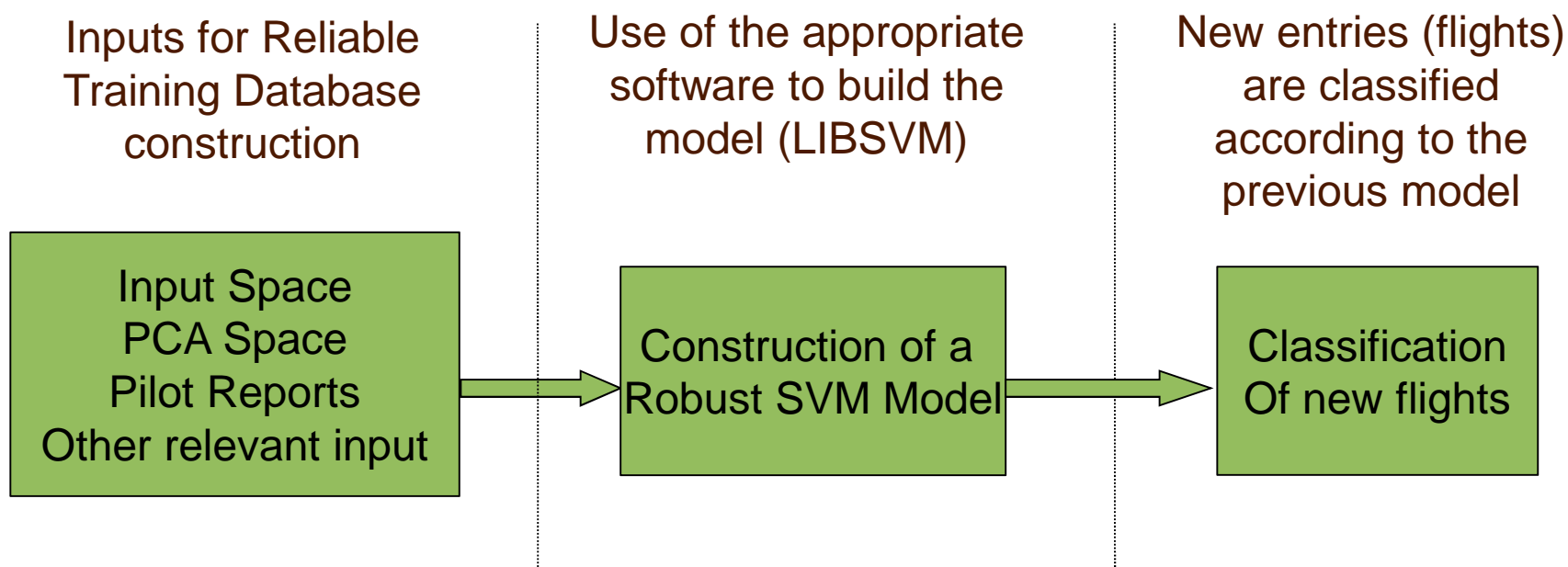
►... That provides the corresponding Label (+1 / -1)

Kernel Machine

- ▶ Real Data is affected by noise, outliers and is not linearly separable normally
- ▶ A mapping function $\Phi(x)$ is used to transpose the data to a space where the SVM can be used directly (linear separation)
- ▶ The SVM classification is operated in the Feature Space



Automatic Classification Process



Software packages used for this process:

- ▶ AGS (Analysis Ground Station) from SAGEM Défense et Sécurité - Safran Group
- ▶ LIBSVM – SVM integrated software from National Taiwan University (GNU License)
- ▶ R statistics Environment from University of Auckland (GNU License)



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Flight data provided courtesy of



Detecting atypical flights

- « When considering a population of flights, an **atypical flight** is a flight which is in a sense different from the majority of the other flights ».
- Atypical flights may present **operational or safety issues** and thus need to be studied by an FDM expert!

Difference with classical procedures

→ Main difference with classical procedures :

- In classical procedures, flights are studied **one at a time**, isolated.
- In ML methods, flights are studied **with respect** to a population of other flights.

→ Some flights may be overlooked by classical procedures but detected by ML methods...

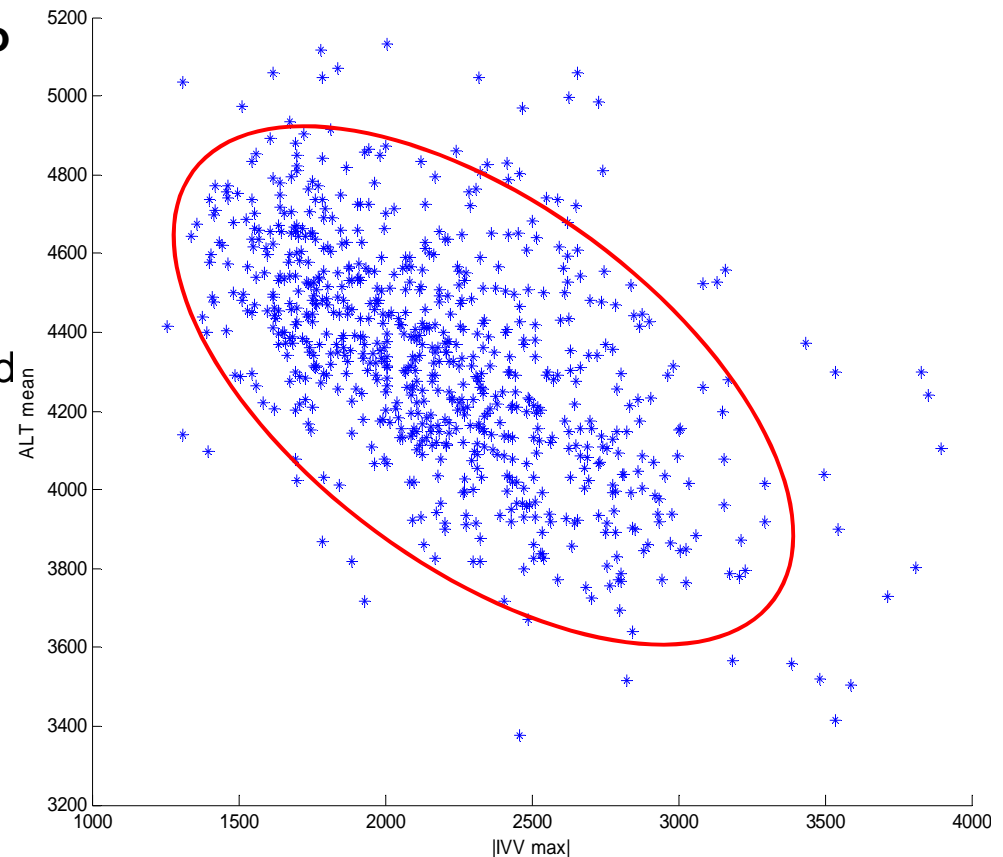
- And vice-versa !

→ ML techniques are complementary with classical detection procedures.

2 parameters Example

→ Example study with 2 « parameters »:

- Data from **721 flights from Porto to Orly**,
- Plotted the mean ALT and max IVV for each flight during **approach phase...**
- **Each point represents a flight.**
- In this simple example, anyone could easily spot which are the atypical flights.



→ ML algorithms do the same, but...

- In **any number of dimensions**,
- For any number of flights,
- And provide **quantitative results**

Choosing a dataset

→ Choosing the dataset is the most important step!

- Garbage in garbage out...

→ There are two decisions:

1. What population?

- All flights that land on Orly? Or all Porto-Orly flights ?

2. What parameters?

- Study trajectory, mechanical parameters? Or engine parameters? Or both ?

Choosing a dataset : what population?

- Some *rules of thumb*: for « kernel methods » (widely used techniques such as SVM)
 - Increasing number of flights...
 - Greatly increases computation time,
 - Mildly increases precision of results.
 - Example: with 10 times the number of flights, the computation time is multiplied by 100, whereas the precision is at best multiplied by ≈ 3.16
 - Good care must be taken when « sampling » the dataset from different sources:
 - With 5 Porto-Orly flights in the middle of 700 Berlin-Orly flights, these 5 flights will be in minority and thus are likely to be considered atypical.

Choosing a dataset : what parameters?

→ It is best to study *groups of parameters* rather than all parameters at once.

- Make several studies:
 - One for engine parameters,
 - One for trajectory parameters,
 - Etc.
- Each study gives a different *point of view*.

→ ***Divide and conquer!***

Choosing a dataset : what parameters?

→ Some other advices:

- In the field of FDM there are many types of parameters, which must not be treated the same way:
 1. Continuous parameters, such as Altitude, N1,
 2. Angular parameters, such as Heading, Roll, Pitch,
 3. Unordered discrete parameters, such as Autopilot mode (OFF/ FlightDirector/ Command)
 4. Ordered discrete parameters, such as FLAP (0, 5, 10, 15, 25, 30)

- Parameters evolve in time,
 - We can take *features* such as mean, max, min etc.
 - Or we can take *snapshots*.

Example study

- We have studied 721 flights from Porto to Orly 26, from **Transavia France**, same aircraft, **from approach till touch down** (10000 feet to 0).

- 14 parameters, in first pass we studied the **mean** of all parameters
 - Position (latitude, longitude)
 - Altitudes, heading,
 - Roll, Pitch
 - Accelerations (angular and along axes)
 - Speeds (vertical and longitudinal)
 - N1.

A word on the mathematics

→ We have used our own detection method:

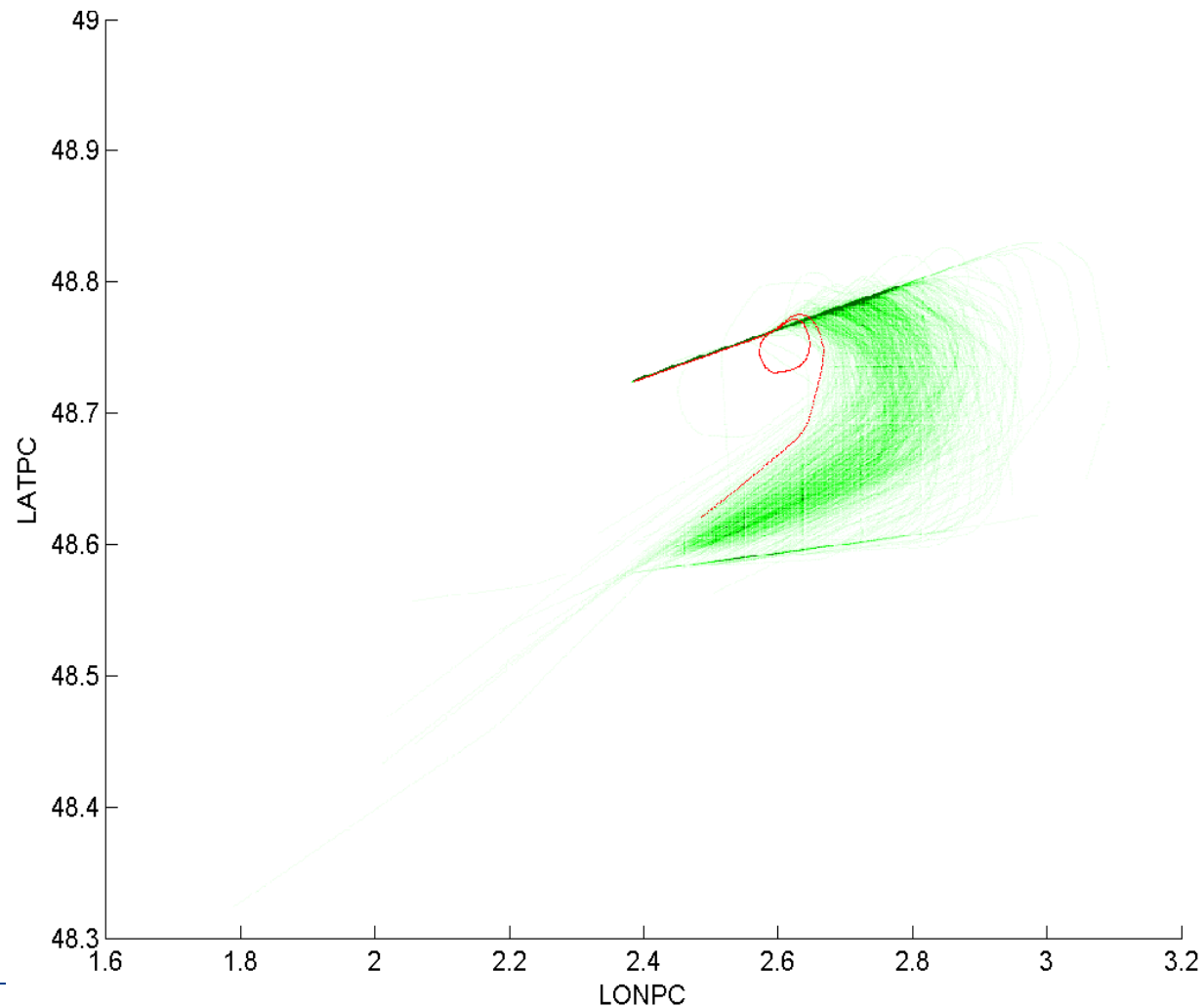
- Based on *Kernel Entropy Component Analysis*, a recent (2010) dimensionality reduction technique,
- Strong theoretical guarantees from nonparametric statistics,
- Better results than state of the art One-Class SVM,
- Very robust even with highly « polluted » dataset.

Results

- Of the 721 flights, **35 are detected**: each flight is given a **pvalue**:
- « A pvalue is the probability that, **under normal conditions**, a flight at least as extreme could occur by chance alone »
 - A flight with a $pvalue < 0.01$ is considered very likely to be an atypical flight,
 - A flight with a $pvalue < 0.001$ is considered extremely likely to be an atypical flight.

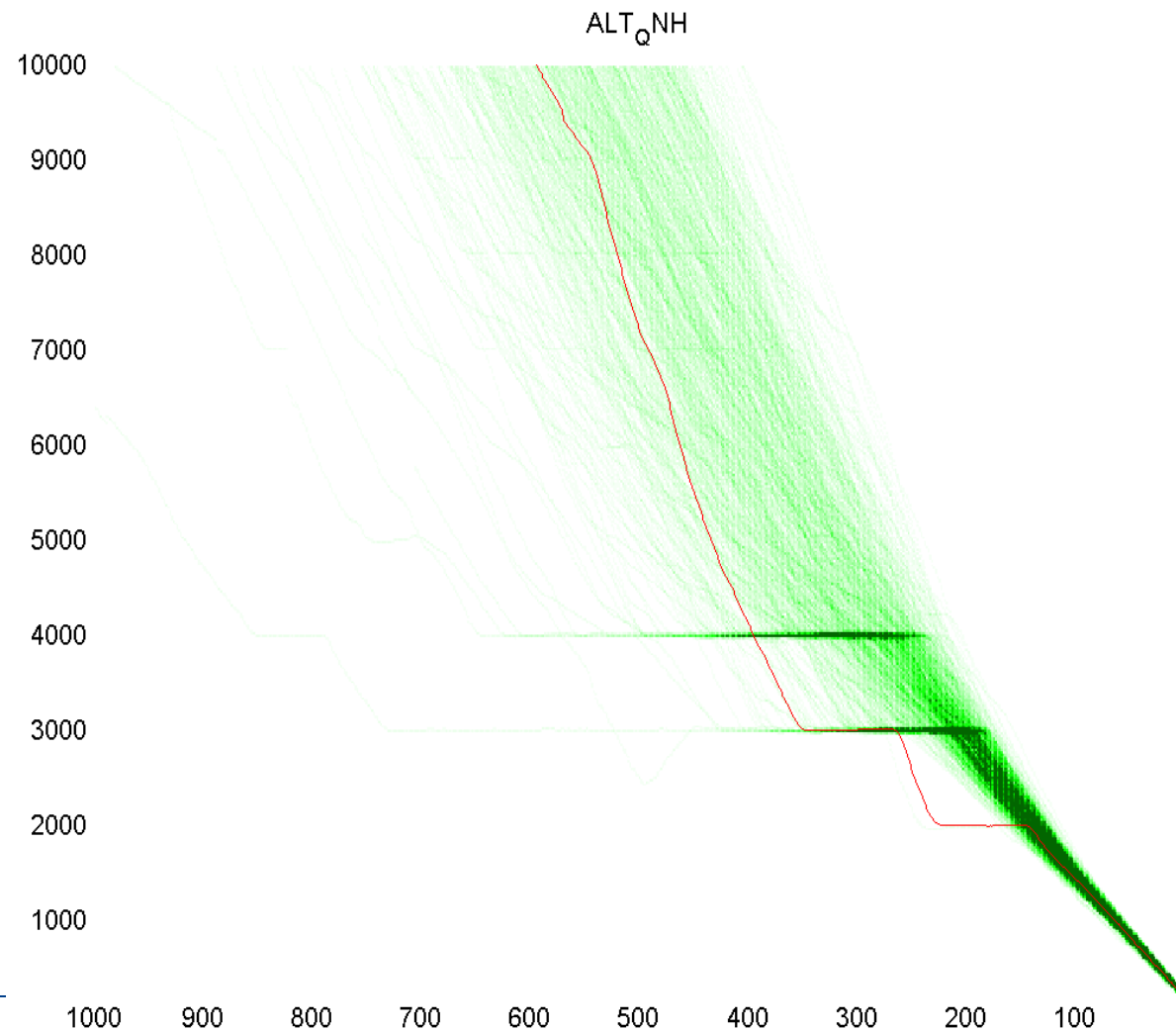
Example of atypical flights

→ Atypical flight 1: pvalue = 0.0000000001, **trajectory plot**



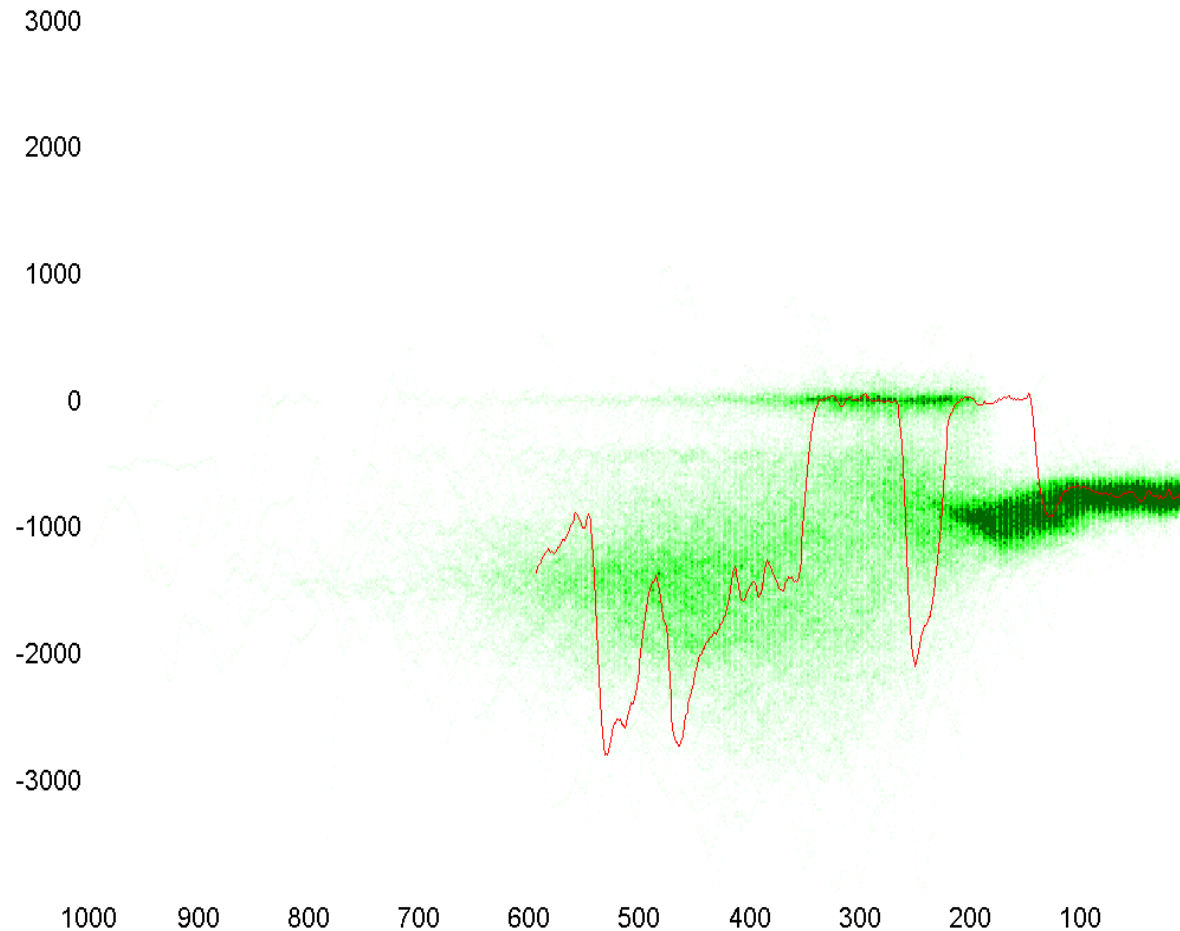
Example of atypical flights

→ Atypical flight 1: pvalue = 0.0000000001, **altitude plot**



Example of atypical flights

→ Atypical flight 1: pvalue = 0.0000000001, **vertical speed plot**



Example of atypical flights

→ Atypical flight 1: pvalue = 0.0000000001, **air speed plot**



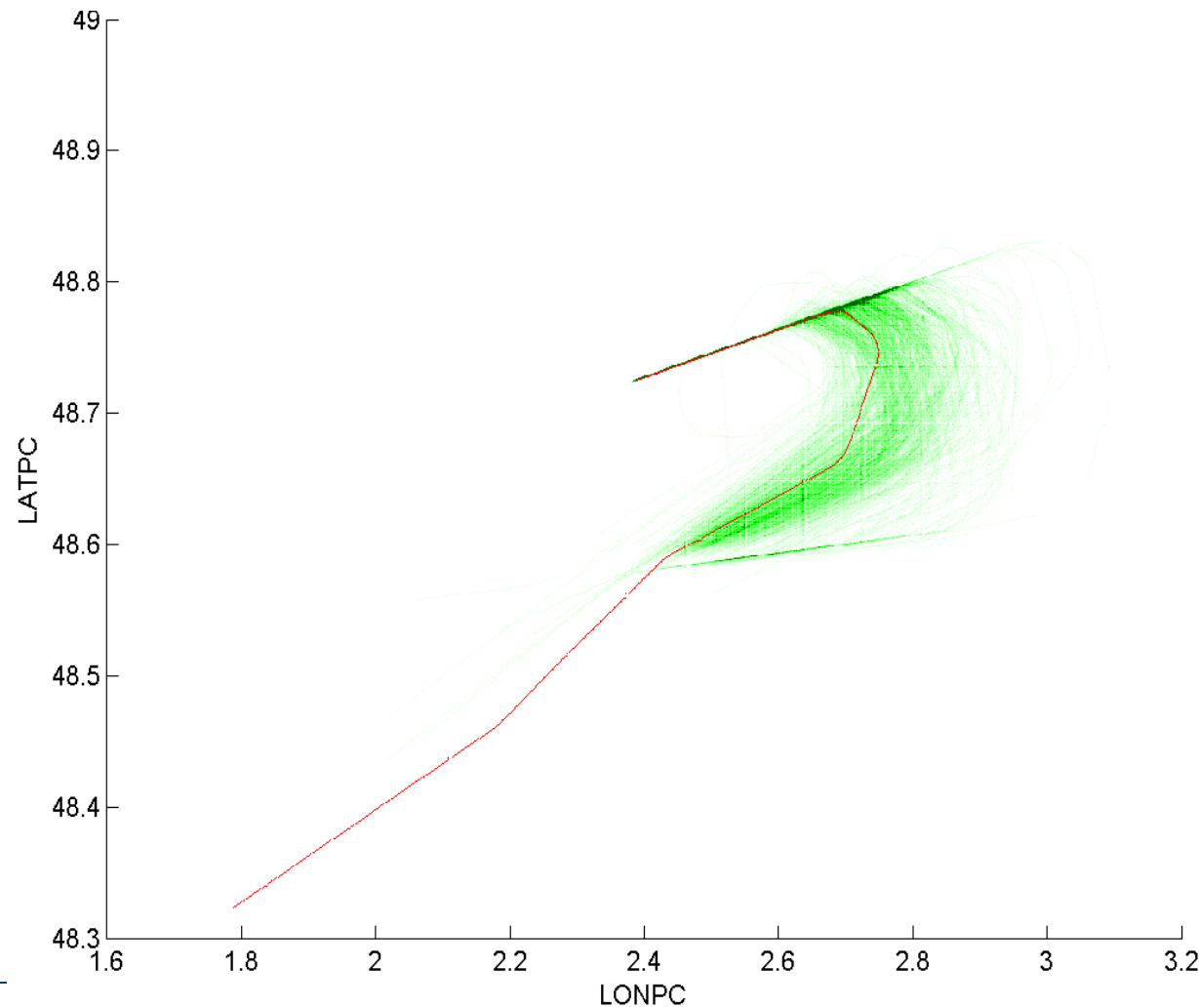
Example of atypical flights

→ Atypical flight 1: pvalue = 0.0000000001

- Classical analysis:
 - Only one event: High Vertical Speed approach, class 1
- Diagnostic:
 - Meteo is clear,
 - Probably due to operational constraints.

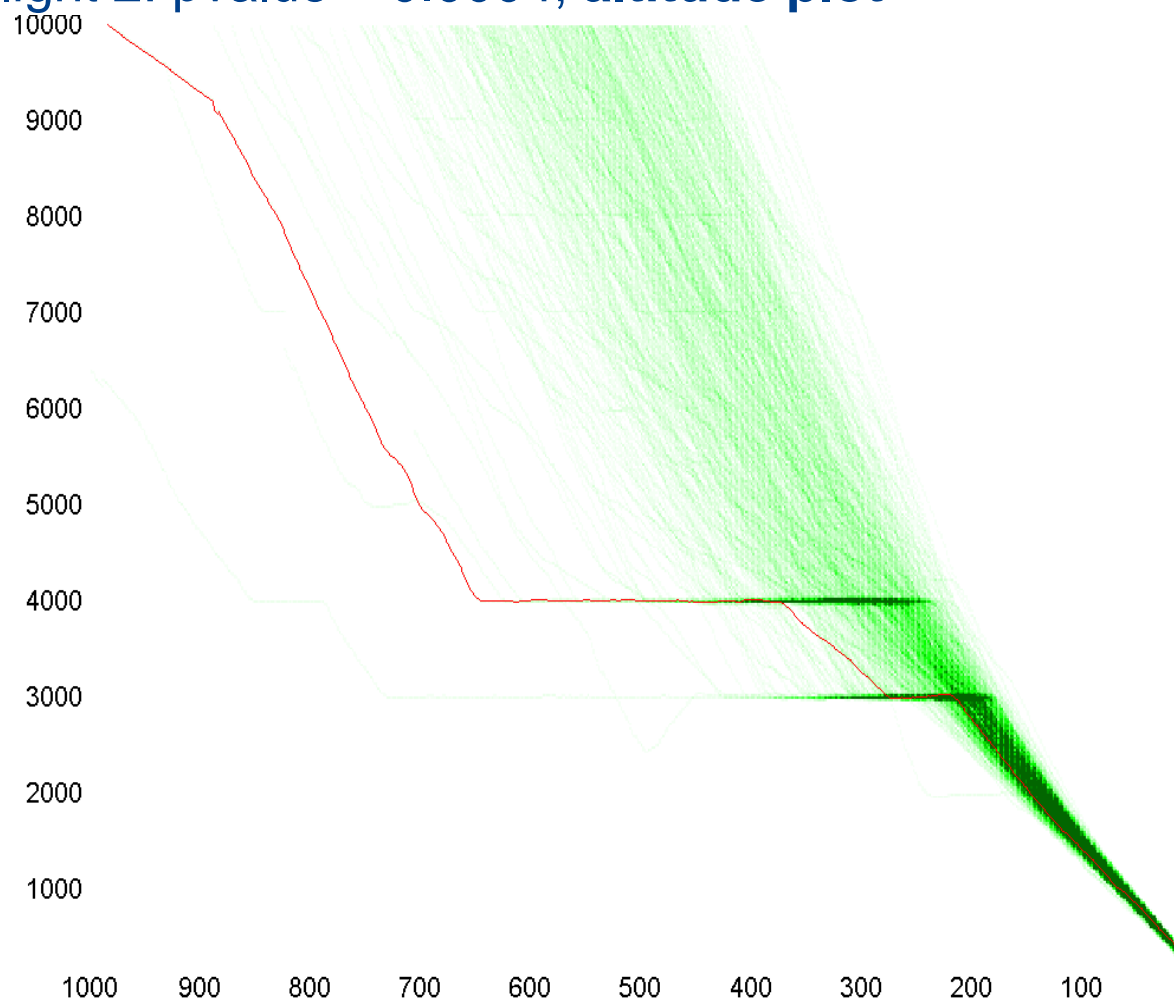
Example of atypical flights

→ Atypical flight 2: pvalue = 0.0004, **trajectory plot**



Example of atypical flights

→ Atypical flight 2: pvalue = 0.0004, **altitude plot**



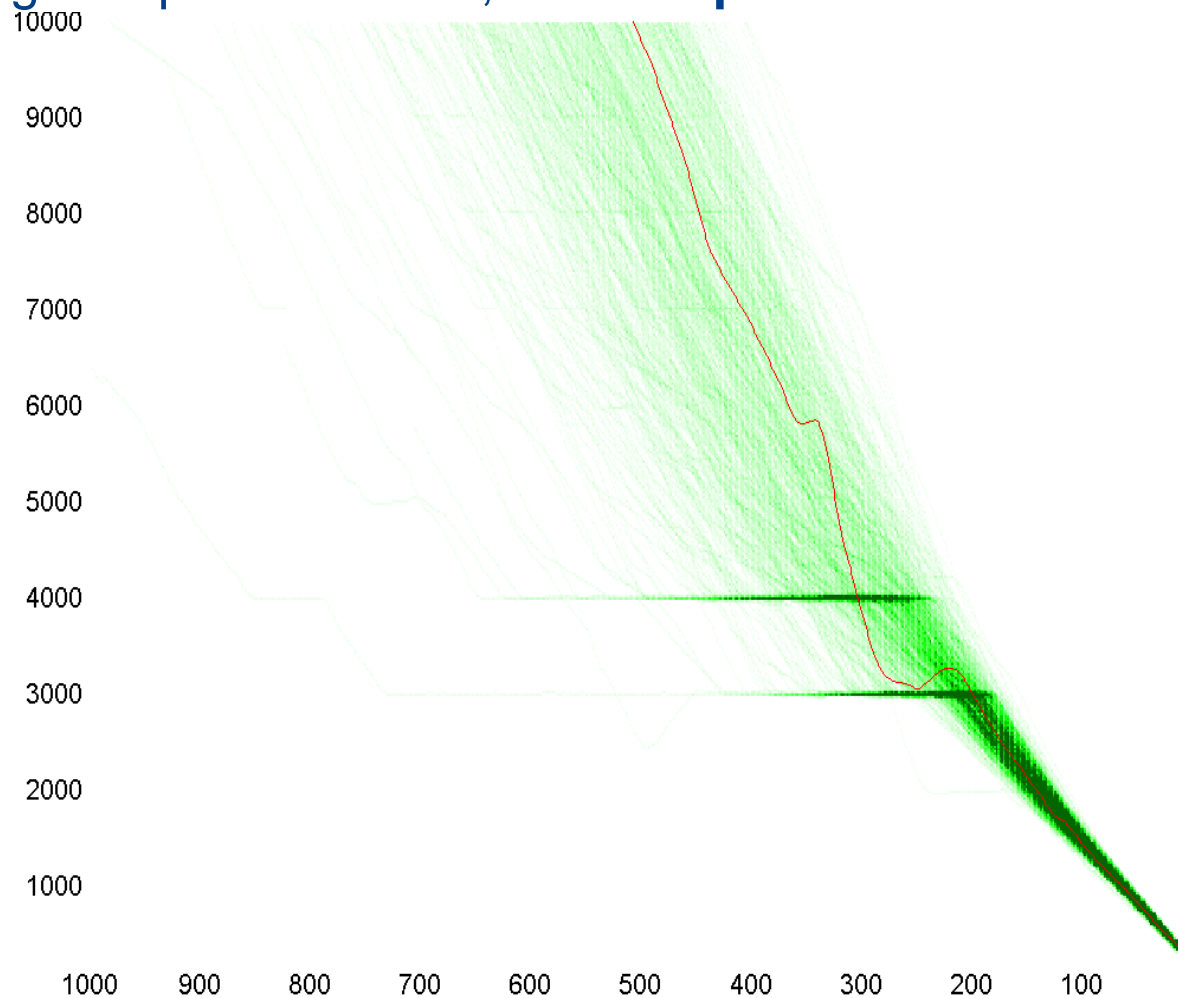
Example of atypical flights

→ Atypical flight 2: pvalue = 0.0004

- Classical analysis:
 - **No event detected** with the classical analysis.
- Diagnostic:
 - Meteo: thunder; cumulonimbus clouds, towering cumulus clouds observed
 - Meteorological constraints: the pilot had to lower his altitude to avoid the cumulonimbus cloud.

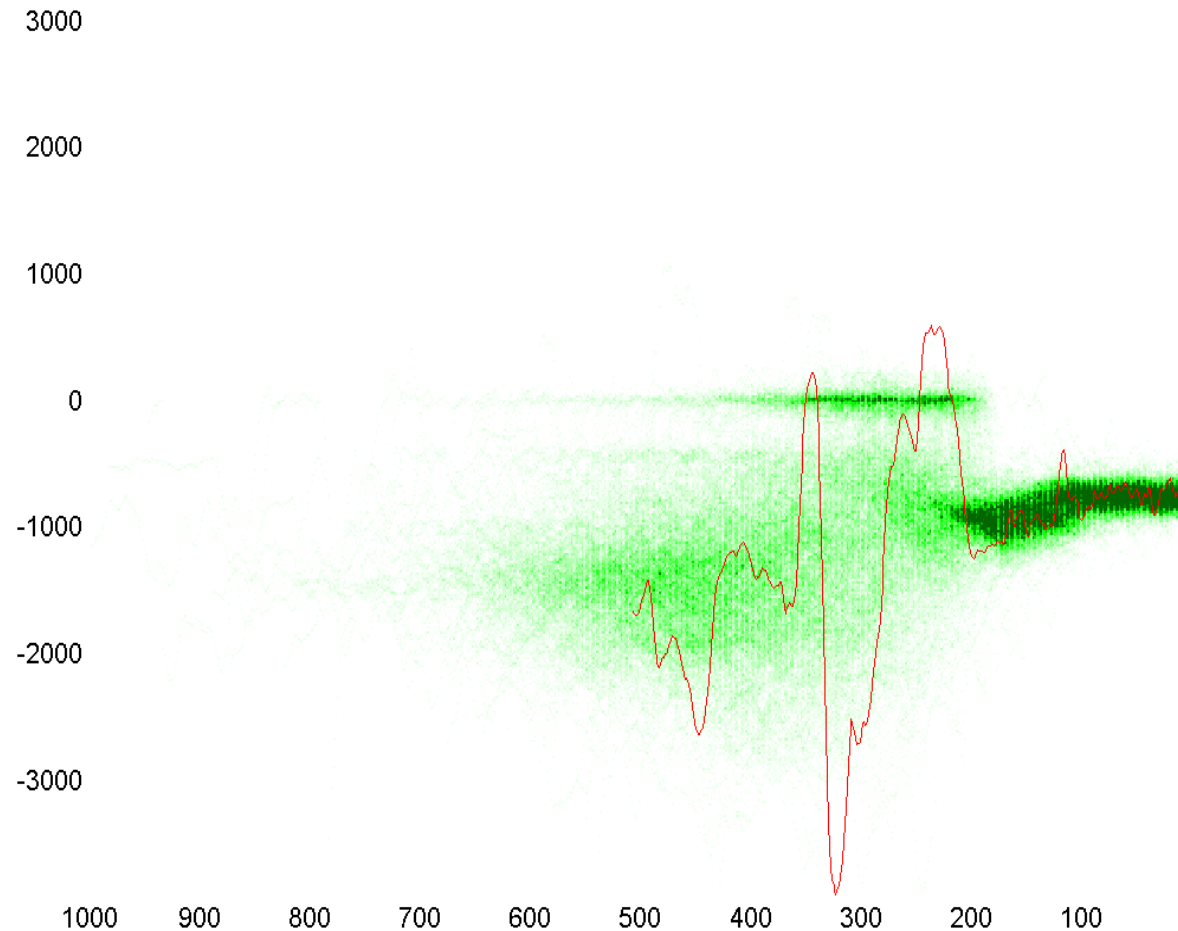
Example of atypical flights

→ Atypical flight 3: pvalue = 0.02, **altitude plot**



Example of atypical flights

→ Atypical flight 3: pvalue = 0.02, **vertical speed plot**



Example of atypical flights

→ Atypical flight 3: pvalue = 0.02

- Classical analysis:
 - One event detected: High Speed - Below 5,000FT, class 1
- Diagnostic:
 - There is a very high vertical speed 300 seconds before touchdown, and irregular altitude profile.
 - This was not detected by classical procedures.

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Conclusion

- **A good « feel » of the data is more important than complicated mathematical algorithms.** Thus FDM experts must be involved during the conception of algorithms.
- Machine Learning has proved its usefulness as a powerful tool in complement to classical event detection procedures.
- **Good graphical representations** are key to the comprehension and interpretation of Machine Learning results.
- Up until recently, Machine Learning was very rarely applied to FDM, so there are many exciting things to discover!

Thank you