

Slido: #IAM2024



In cooperation
with:



Enabling VLL operations far from airports



Moderator

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Enabling VLL operations far from airports

Goal:

- To remind the technical difficulties and associated. challenges to safely enable VLL operations far from airports.
- To present solutions applied to support the operations in different environments.
- To identify and propose generalisation of good practices and working operational framework.

Air Risk Methodology for BVLOS operations

www.thalesgroup.com

BVLOS Operations in VLL : Incremental Roadmap

2020-2021

2022-2024

2025

PHASE 1 ●

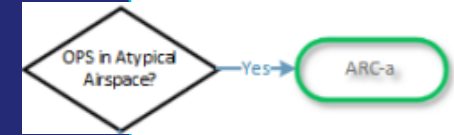
PHASE 2 ●

PHASE 3 ●

Full DVR SAIL III

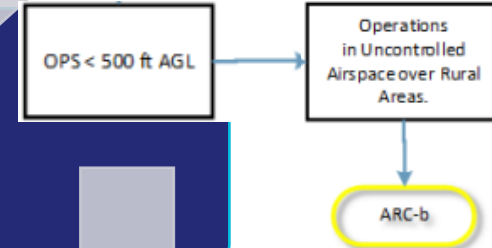
PHASE 1

- BVLOS Operations **in Temporary Restricted Area in Rural areas** (experimental flights).



PHASE 2

- BVLOS Operations **in Uncontrolled Airspace over Rural Areas**.
Exposure time: 10h/month



PHASE 3

- Same than Phase 2, « routine » operations.



Manage Air Risk : Process Scheme

> 4 steps

▸ Strategic analysis

- During Flight Plan elaboration
- List of protocols to do

Months before

> Information post-strategic

- Warning to other users of crossed airspace

Months before

> Pre-tactical analysis

- Last time / real time information (radio, phone calls, ...)

Day(s) before – D-day

> Tactical management

- During flight procedures

During flight

And tomorrow...

> Enhanced tools and method to foster operations in uncontrolled airspace

> Input from another ASD and Eurocae Member.



Enabling VLL Operations

EUROCAE WG105 activities on DAA for VLL

- To facilitate UAS operation in VLL, a performance based air risk mitigation is required
- Within EUROCAE WG105 Industries and research organization (NRCC) are working together to define a DAA MOPS for UAS in VLL

Performance based approach

- Surveillance performance requirement flown down from Risk Ratio (ARC B, ARC C) thanks to Monte-carlo simulation.
- Industry feedback on feasibility
- Statistical models: UAV trajectories, UAV parameters, Sensor models, Encounter model
- The proposal is to provide to the industry
 - Validated functional and performance requirements
 - Methodology for specific future application
- ED-330 Document to be published in 2025

US and Canadian data used for validation

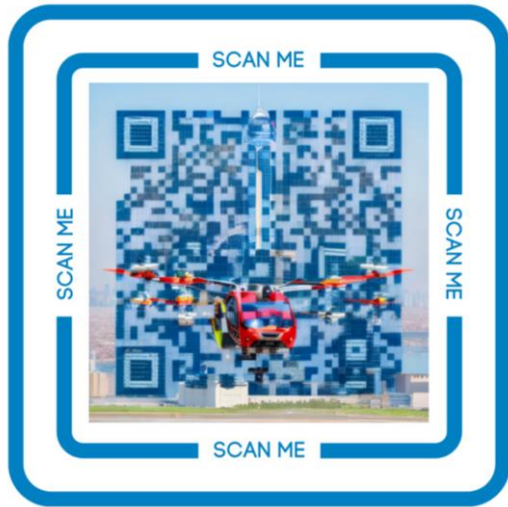
- EU data on VLL traffic and encounter model welcome



Thank you

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 Alliance for New
Mobility Europe

 ASD

 DRONE
ALLIANCE
EUROPE

 Global UTM
Association

 JEDA
Joint European Drone Associations

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far from airports**

Today possible?

DRONIQ FOR FLIGHT



EASA

Innovative Air Mobility
Implementation Forum

DRONIQ 

Drones are „invisible“

Limitation of full drone potential



Drones are **invisible** to manned aviation, air traffic control and other operators, especially in uncontrolled airspace.



**LIMITATION OF
COMMERCIAL DRONE
POTENTIAL AND USE**

BVLOS within CTR

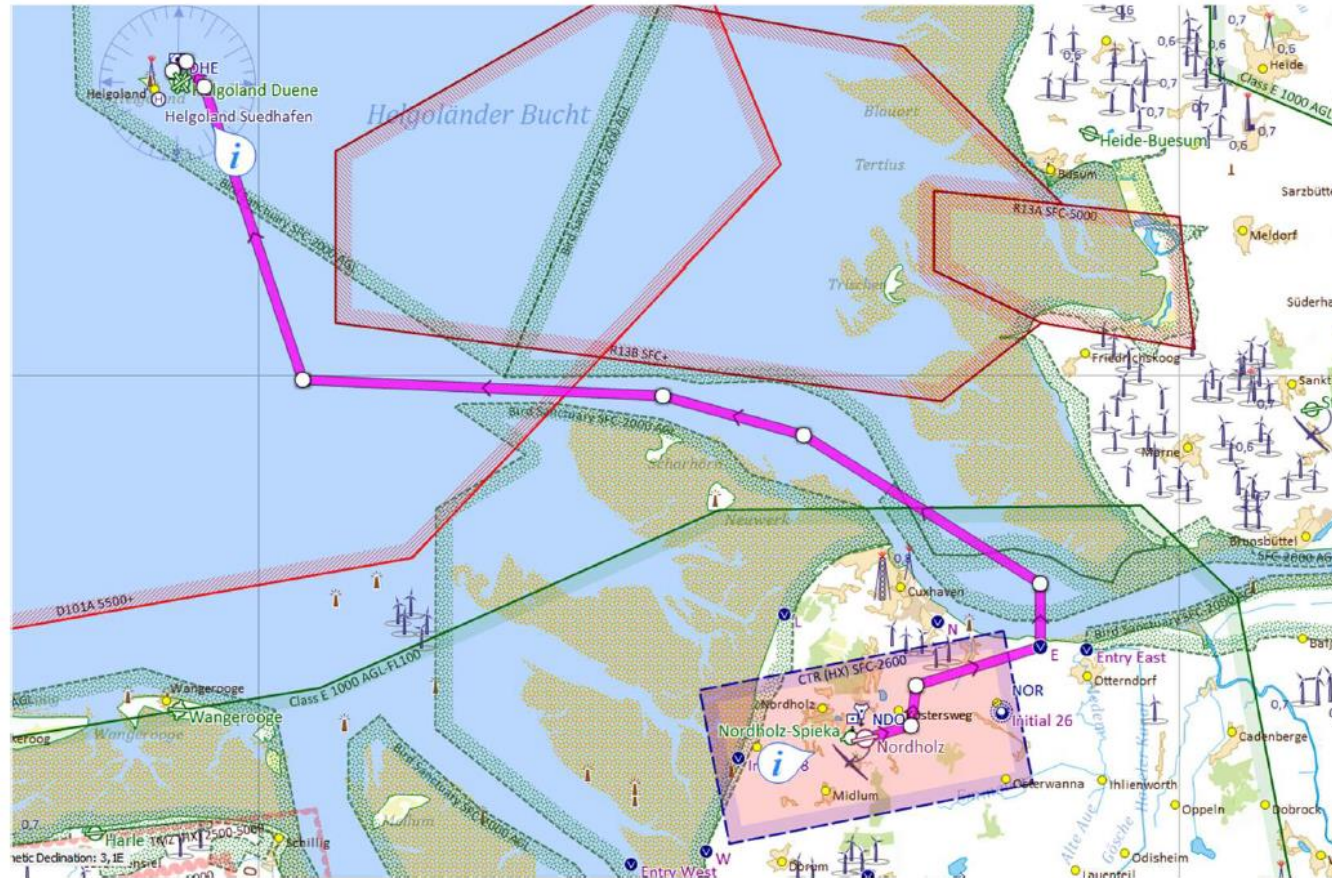
- ANSP will separate manned and unmanned air traffic
- Certified Mode-S transponders can interfere with the communication of the drone with the linked ground station due to their power
- Low power (non-certified) Mode-S transponders should be accepted for the VLL-airspace
- The height at which the airspace for manned aviation begins in principle must be redefined and must be accepted by each competent authority in this way
- Guidelines for UAS operations in the open and specific category – Ref to Regulation (EU) 2019/947

BVLOS outside controlled airspace

At least 50% of the surrounding air traffic must be detected - How?

- iConspicuity is the solution for detect and avoid
- In addition to the u-Space with its services, there should be UAS-geographic zones or airspace elements for manned aircraft with high traffic density in which the use of an iConspicuity-capable transceiver is mandatory for all aircraft, manned or unmanned.

... but possible!



2024 EASA IAM Forum – enabling VLL operations far from airports

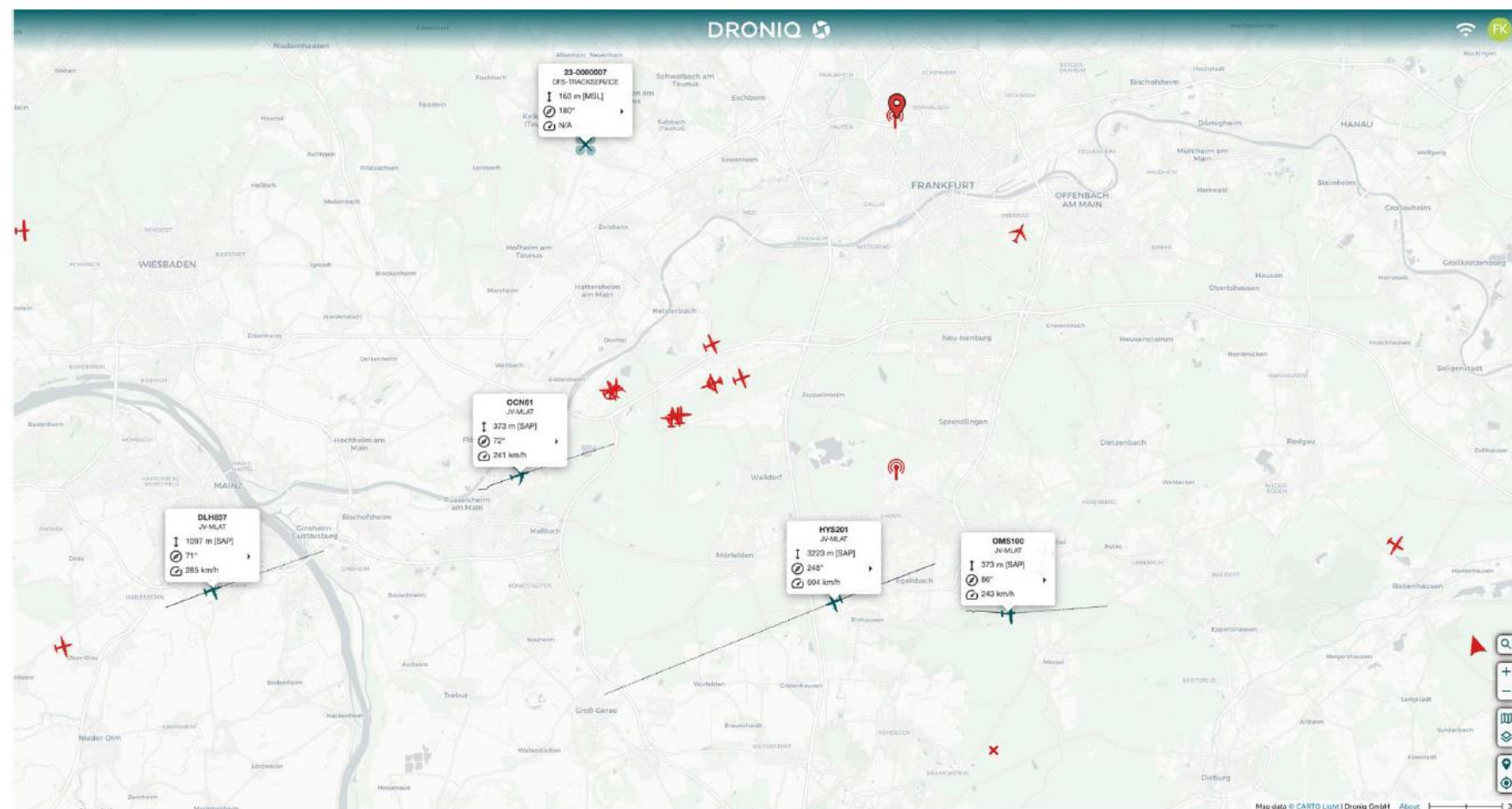
- Alt max. 600ft AGL bzw. AMSL
- Approach and landing in Nordholz via published VFR Routes
- Approach and landing in Helgoland via published traffic patterns
- Use of air-to-air communication and use of mode-S transponder
- Compliance with minimum meteorological conditions for flight visibility, ground visibility and cloud clearance in accordance with SERA.5001 for airspace G and D (CTR)

Hanseatic S360Mk.II – equipment list



Spannweite	3600 mm
Max. Startgewicht	< 25kg (3,5l Tank) < 30 kg (8l Tank)
Betriebsfrequenz	2.4 GHz 1616 - 1626.5 MHz 868 MHz
Max. Steig- / Sinkgeschwindigkeit	5 m/s bzw. 1000 ft/m 2,5 m/s bzw. 500 ft/m
Höchstgeschwindigkeit	150 km/h bzw. 80 <u>kn</u>
Reisegeschwindigkeit	100 km/h bzw. 55 <u>kn</u>
Max. Flugzeit	3.5 Liter Tank: 3 h 8 Liter Tank: 7 h
Flugfunk	Trig TY91 D-PDQO (zugeteilt)
Mode-S Transponder	ping200X 24-bit Adresse (zugeteilt)
Beleuchtung	2 Navigationslichter 1 Antikollisionsblitzlicht
Anti Kollision	FLARM in / out ADS-B in

Best date solution – combined air traffic view



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Enabling VLL Operations

Kevin Houston

President Drone Alliance Europe

& Head of Regulation MANNA Drone Delivery



Who is MANNA?

- Founded 2019 - Bobby Healy (Serial Entrepreneur)
- Relies on Private investment
- 120 employees in 6 countries (mainly Ireland)
- Designs its own automatic Drones (55 Engineers)
- Manufacturers its own Drones
- Operates its own Drones
- LUC from IAA in April 2021

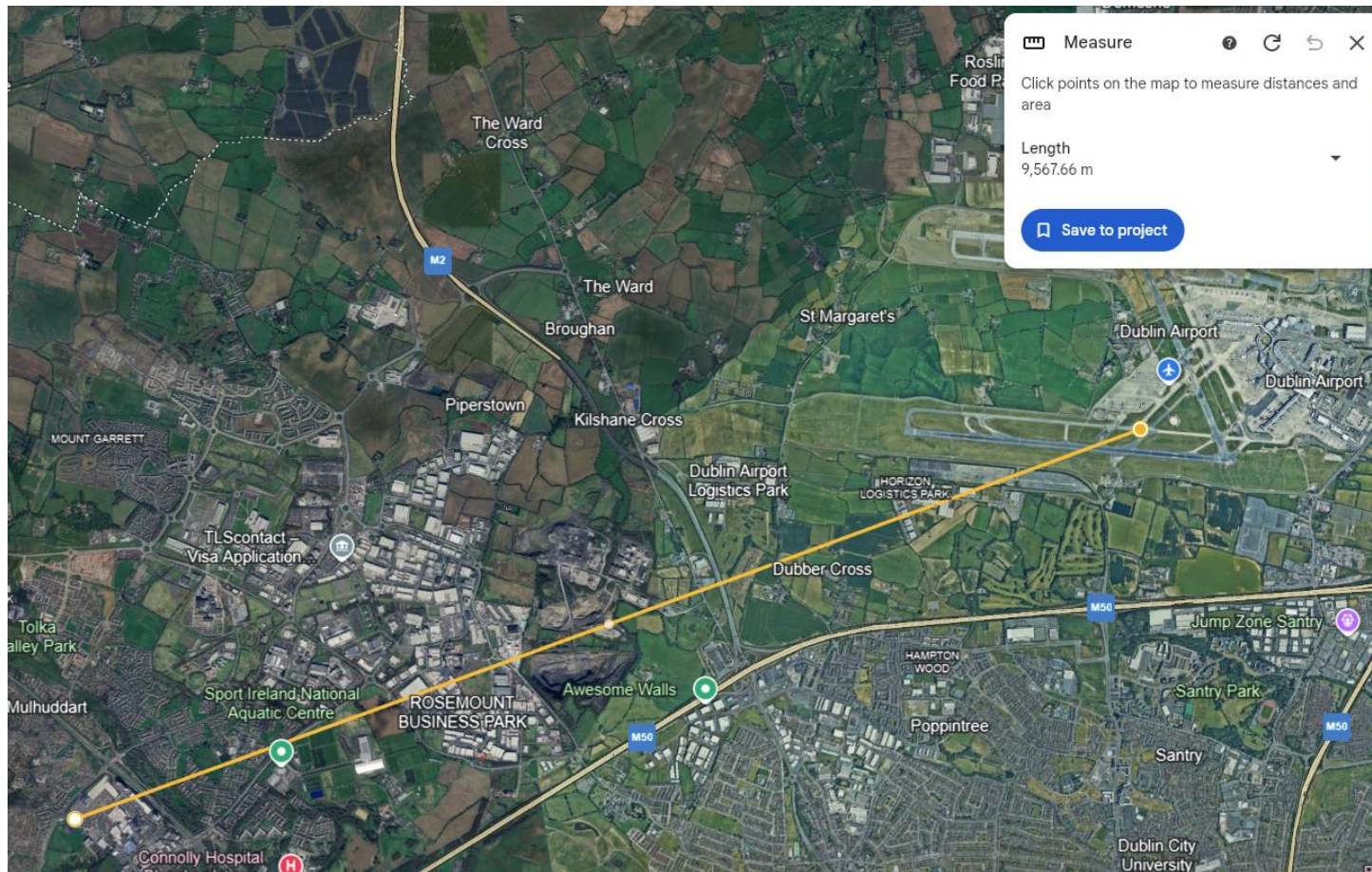


Solution – UAS Geographic Zone

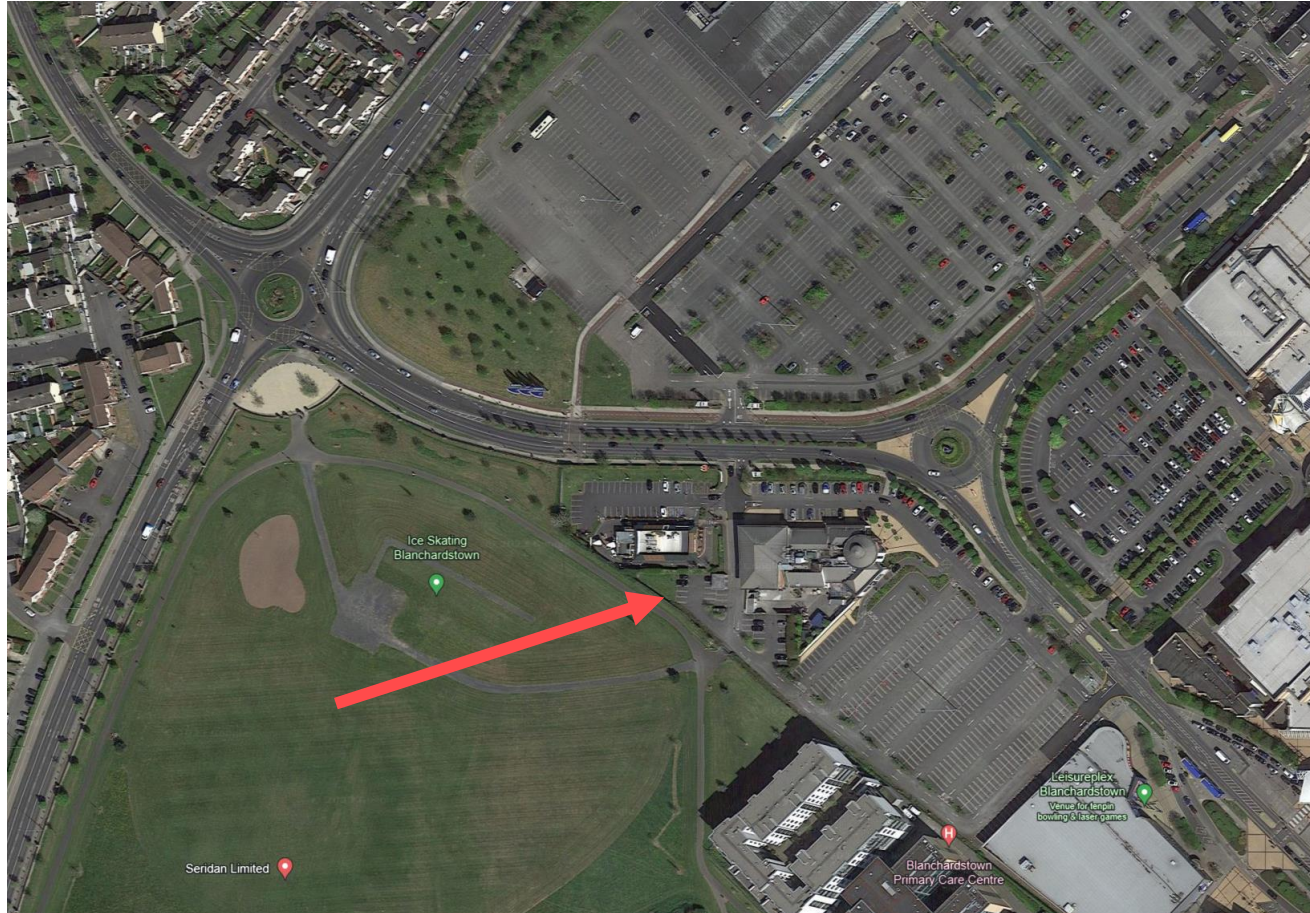
- MANNA Drone Delivery is the nominated controller
- ANSP (Air Nav Ireland) & NAA (IAA) developed in parallel
- Has worked without problem since March 24
- Operators have no restrictions



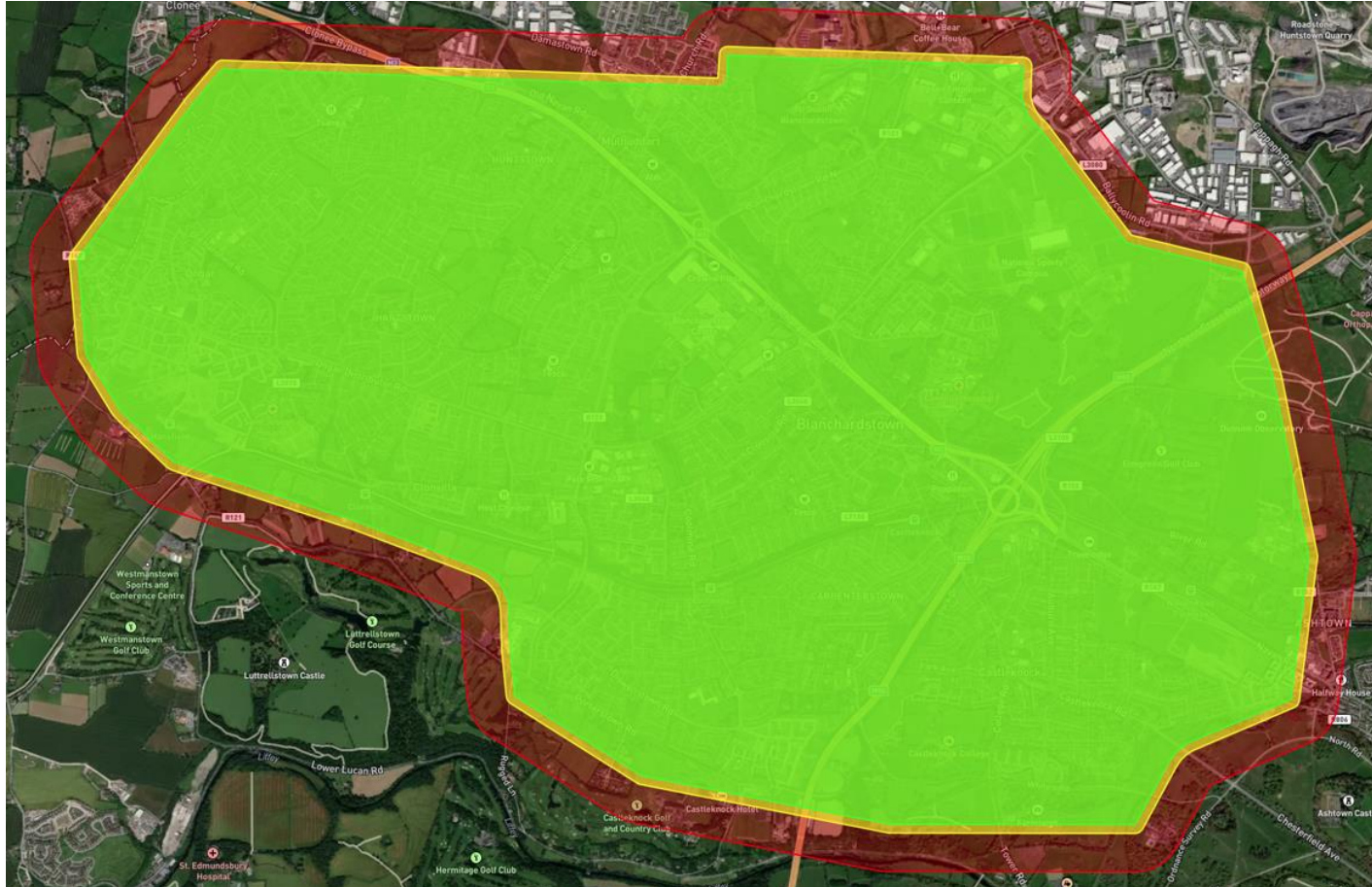
Blanchardstown – 10Km from Airport



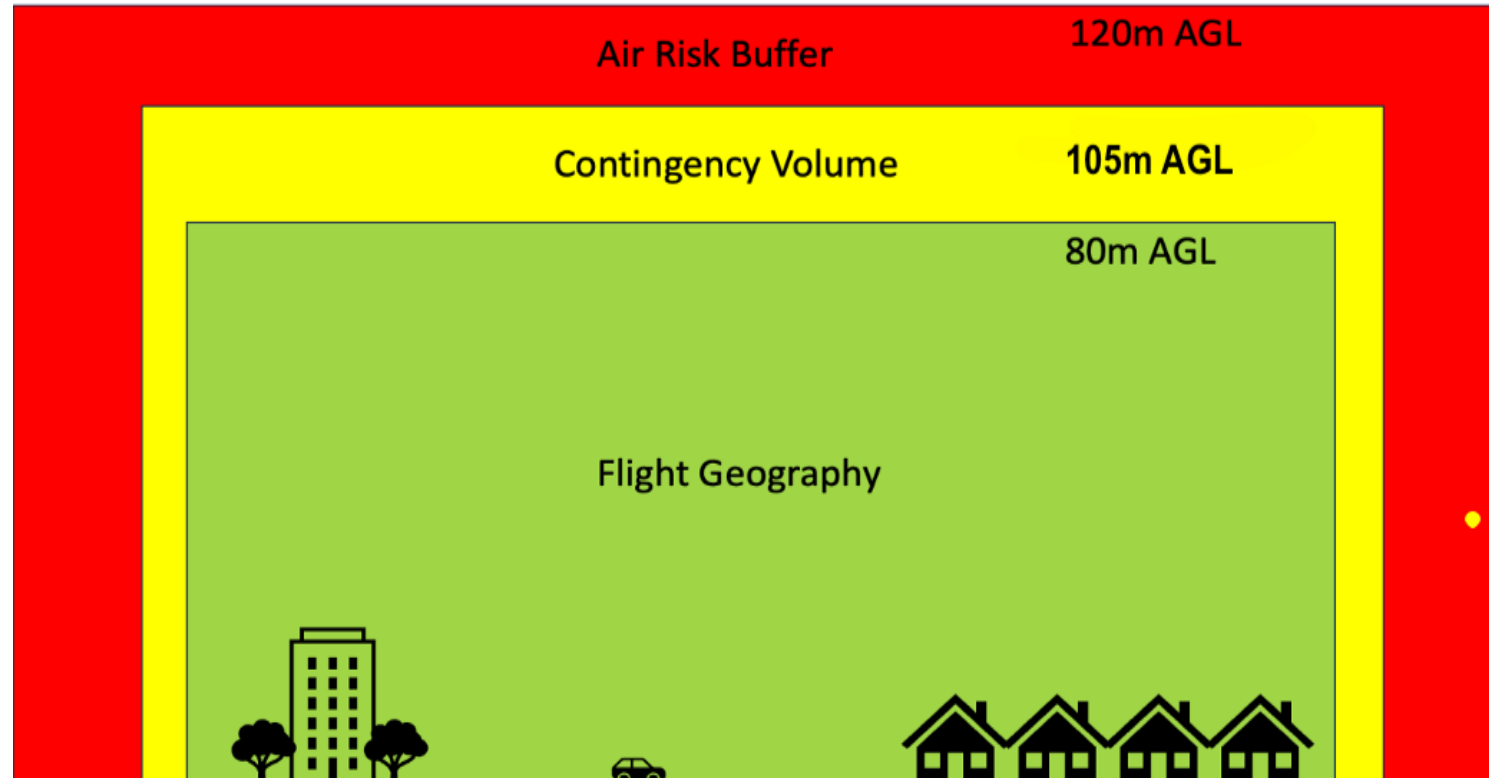
Main Base



Flight Geography



Altitude



Memorandum of Understanding

APPENDIX F –

MOU & Vol Coordinates

Agreement Between
MANNA AERO and AIRNAV Ireland
For
UAS Operations in a Geo Zone
Blanchardstown

Geo Zone Volume & Coordinating Procedures

There the area to be operated as a result of the formal written assessment by ASAP dated 16 Mar 2024.

Signed

Cathal Mac Criostail, Manager Airspace & Navigation
AIRNAV Ireland

Signed



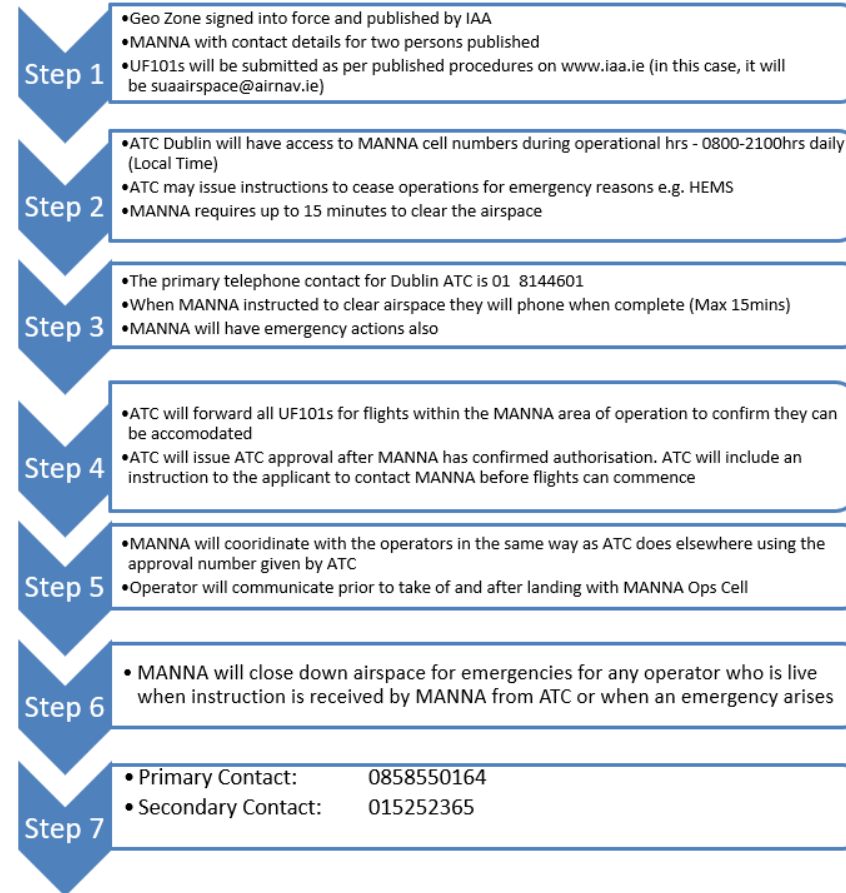
ROBERT HEALY
ACCOUNTABLE MANAGER



Coordinating Procedures

Coordinating Procedures

P-004 SOP – Ops Manager – Management of Airspace & Third-Party Operators





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Schweizerische Eidgenossenschaft
Confédération suisse
Confederazione Svizzera
Confederaziun svizra

Bundesamt für Zivilluftfahrt BAZL
Office fédéral de l'aviation civile OFAC
Ufficio federale dell'aviazione civile UFAC
Federal Office of Civil Aviation FOCA

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Larissa Haas

23/10/2024 IAM Implementation Forum



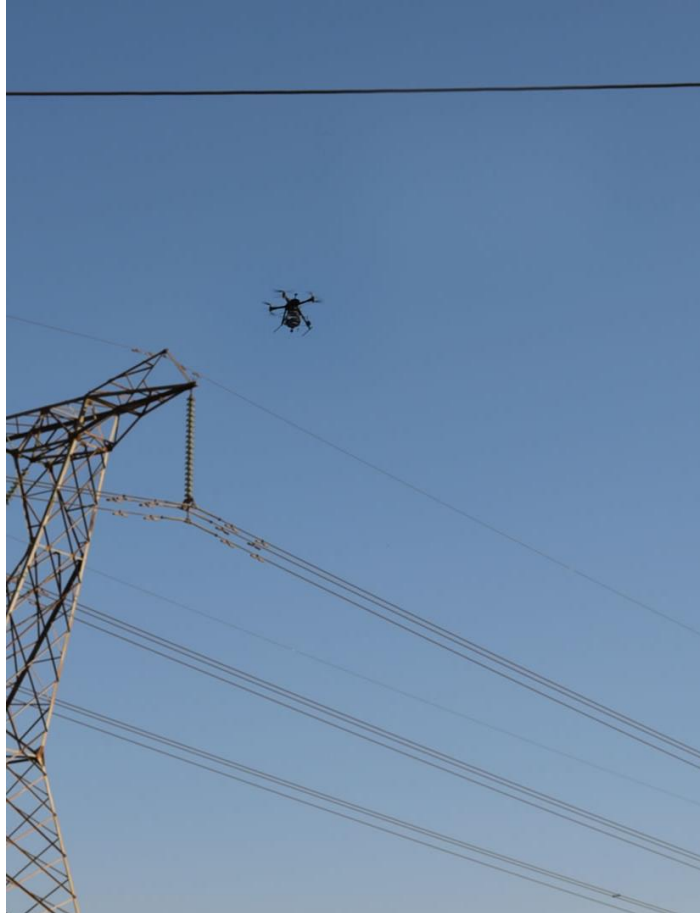
VLL OPERATIONS ARE A CHALLENGE

Copyright: Annalena Gertsch

Aerial objects by group			Hazard Identification			Risk Characterization	
Cat	Group	Description	Considered as Hazard [yes / no]	Equipment Conspicuity	Traffic Characteristics <i>Rationale to not consider it as Hazard</i> Hazard characterization within airspace and details on conspicuity requirements	Strategic Mitigations (included in SORA) <i>*Soft factors (excluded from the SORA scope)</i>	Tactical Mitigations (included in SORA) <i>*Soft factors (excluded from the SORA scope)</i>
1	F	Fauna. Large Birds	No	None	(e.g.) Impact on Ground Risk only		
	K	Kites and tethered balloons.					
	B	Hot air balloons.	No	MODE-S (a)	<ul style="list-style-type: none"> Balloons tend to operate in known weather and areas. Traffic exposure at low level is limited in airport environment and controlled airspace For gas and hot air balloons within airspace C and D, an authorisation is required from the appropriate air traffic control units. Minimum VFR height (ie 500ft/AGL) from VRV-L/SERA are applicable to balloons (except for training) and main balloons sites are visible on the ICAO chart for flight planning. (a) Transponder MODE-S only required for flights during aeronautical night and dense fog (VRV-L, art. 29) 	<ul style="list-style-type: none"> Flight planning, identification of the flight time and areas for B Ops Monitoring of radio communication <u>Soft factors</u> Balloons are identifiable on on-board camera / ground-based webcams due to their size	<ul style="list-style-type: none"> Transponder MODE-S detection through MLAT <u>Soft factors</u> Balloons are identifiable on on-board camera due to their size
	P	Parachutists					
	A	Unpowered air sports: hang gliders, paragliders, etc.					
2	R	Radio controlled model aircraft					
	G	Gliders					
	S	Powered air sports: very light aircraft, ultralights, motor gliders, motor paragliders, etc					
3	D	Dirigible airships					
4	H-State	Helicopters (VIP, Police, Customs, Civil Protection, Military)					
	H-SAR	Helicopters (emergency and medical services SAR/HEMS)					
	H-CAT	Commercial rotorcraft (CAT) incl. SPO (Aerial Work)					
	H-GAR	General aviation rotorcraft (GAR)					
	L	Light aircraft (i.e. non-pressurised general aviation).					



Current challenges



1. UAS operators often **lack access** to crucial **information**
2. **Coordinating** with (local) airspace stakeholders requires significant **resources**
3. **Hazard identification** and **mitigation** is not universally applicable



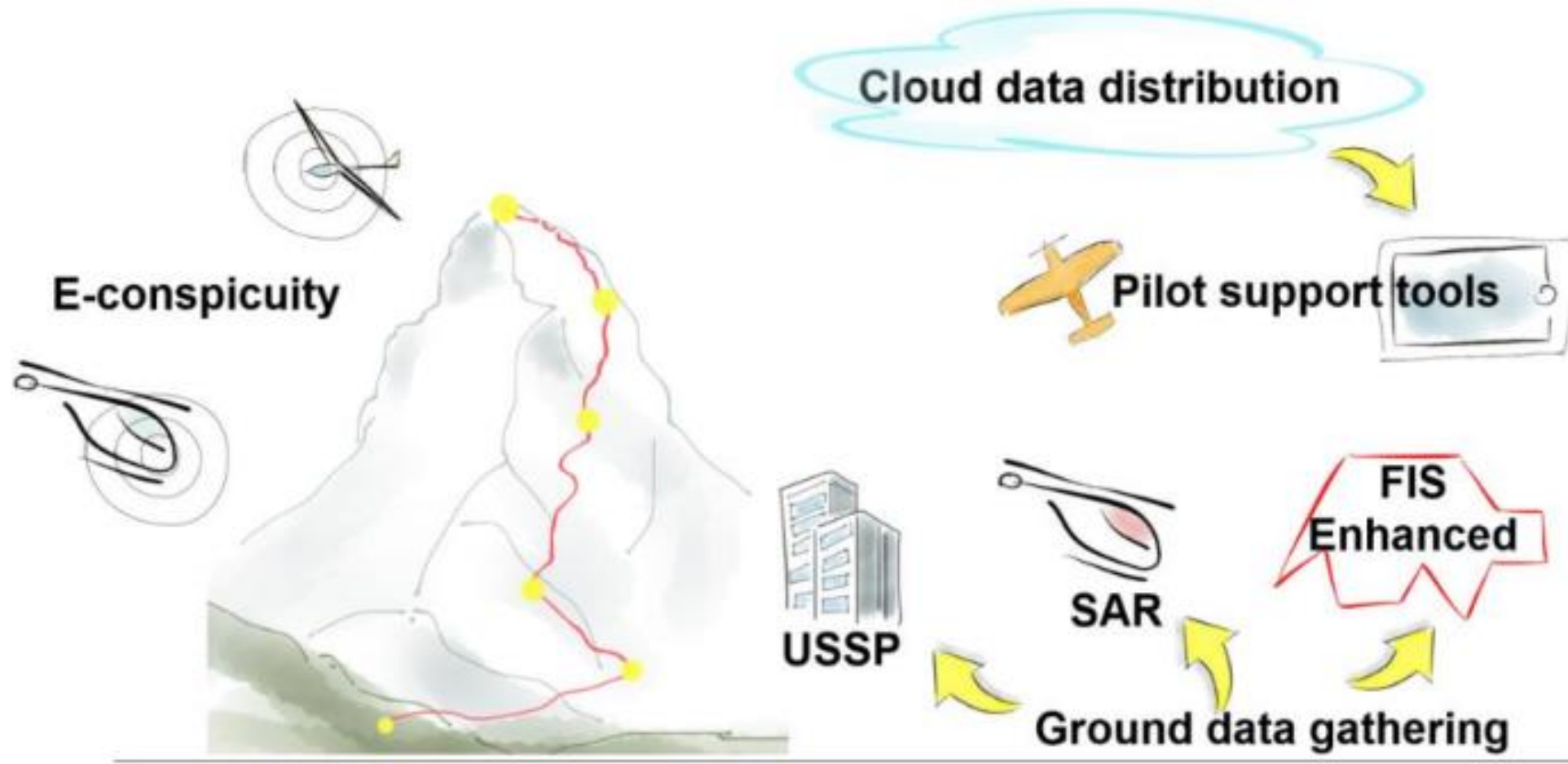
Solution: large-scale e-conspicuity



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2. **Coordinating** with (local) airspace stakeholders requires significant **resources**
3. **Hazard identification** and **mitigation** is not universally applicable



Goal: full e-conspicuity by 2030





In a nutshell

- Growing **recognition** of for enhanced visibility in lower airspace.
- Stakeholder survey (Q3 2024): The Swiss aviation community are early adopters of e-conspicuity devices, **fragmentation and technical differences** among systems remain.
- Switzerland's topography **limits the current CNS infrastructure**, leaving parts without full coverage.
- Switzerland has a strong **industry** developing e-conspicuity solutions and supporting services.
- **Cost-efficiency** is possible by creating a **framework** for the use of **low-cost, non-certified** technologies.
- Challenge: **Building trust** in these technologies.
- Solution: Fostering **test** and **demonstrations** to achieve proof of concept.
- European-wide **collaboration** and **coordination**.