













MLEAP STAKEHOLDERS DAY

#2

Paving the way for the future of Artificial Intelligence in Aviation



MLEAP project: [Machine Learning Application Approval]

May 17th 2023





Introduction of the MLEAP project and of the Partners

Presentation of the use cases

Presentation of the single public deliverable

Q&A session

COFFEE BREAK

Presentation of the objectives and progress of Task 1 (data management) Swen RIBEIRO, LNE

Presentation of the objectives and progress of Task 2 (generalisation guarantees) Thiziri BELKACEM – Jean-Baptiste ROUFFET, Airbus Protect

Presentation of the objectives and progress of Task 3 (robustness guarantees) Arnault IOUALALEN, NUMALIS

Conclusions & Next Steps

Networking Lunch



Who we are > > >

Consortium members:



EASA

Willy Sigl, Xavier Henriquel, Guillaume **Soudain, François Triboulet**



AIRBUS

PROTECT

Airbus Protect

Michel Kaczmarek, Thiziri Belkacem, Jean-Baptiste Rouffet, Jeremy Bascans, Matthieu Rochambeau

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LNE

Olivier Galibert, Swen Ribeiro, Agnes Delaborde, Sabrina Lecadre



Numalis

Arnault Ioualalen, Noémie Rodriguez





Founded in 1901 - Appointed by French government on testing, certification and metrology for Industry (all sectors)



Al evaluation Department

Development of evaluation standards

Al systems testing

Development of certification schemes

Development of testbeds

Professional training for industry

950+ systems evaluated in all major domains of Al and robotics since 2008









Development of softwares for AI evaluation and data preparation



www.lne.fr/logiciels/lne-matics

Certification for AI processes (2021)



https://www.lne.fr/en/service/certification/certification-processes-ai

LEIA 1/2/3: testbeds for AI and robotics (simulation, physical, hybrid)











Numalis, the no-guess company

- Formal methods for AI systems
- Markets: Aeronautic, Defence, aerospace, railway, health
- SaaS solution to
 - Measure robustness
 - Explain behavior
 - Prepare compliance of IA
- 20 persons, Montpellier



On-going projects:

HE MLEAP with EASA 2 EDIDP (Defence) ESA...









saimple



- Al Robustness
- Al Explainability
- Formal analysis
- Trustworthy AI



Standardization:

- ISO/IEC standard editor on Al robustness
- Contributor to many other projects

numalís

Services:

- Standardization ecosystem
- Validation process
- Al Audit



/ Airbus Protect

: What we do

Consulting

on Safety, Cybersecurity and Sustainability to optimise performance and support our customers on regulatory compliance and certification

Innovation

We are involved in research projects & member of institutional working groups

Training

We are a recognised training organisation

Software

Specialised software supporting endto-end safe mobility activities

R&T & software development projects in Al:

DEEL project for IRT Saint Exupéry and ANITI
Confiance AI project
EPI project for IRT SYSTEMX (Consortium with
STELLANTIS, NAVAL Group, EXPLEO, LIP6)
PRISSMA project for French Ministry of Transportation

an {Airbus} company

bringing together outstanding expertise in safety, cybersecurity and sustainability we created a European leader in risk management

... delivering consulting, services & solutions

Day 2: MLEAP Stakeholders' Day Introductory notes from EASA technical team



Guillaume Soudain
EASA AI Programme Manager
MLEAP Project Sponsor

Xavier Henriquel EASA Safety Expert MLEAP Tech Lead



François Triboulet
EASA ATM/ANS Expert
Coordinator

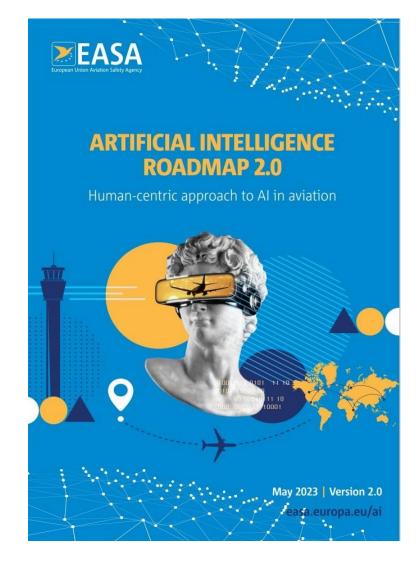




EASA AI Roadmap - Towards AI trustworthiness

- → Impact on all aviation domains
- → Common issues for safety-related applications
- → « Al trustworthiness » concept is the key!

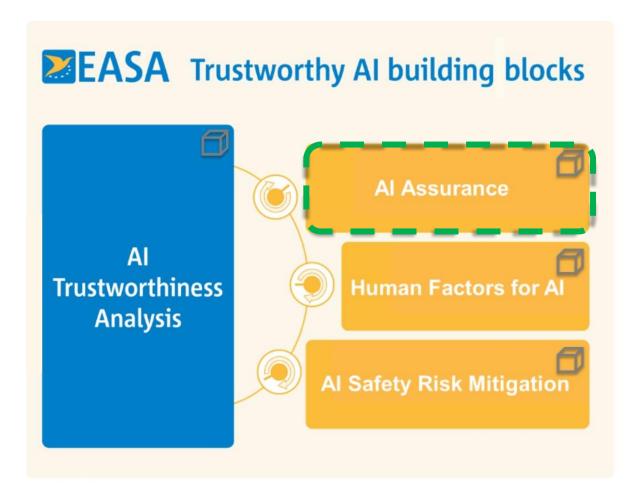






EASA guidance for Level 1 & 2 ML* applications







TOP3 challenges for Level 1&2 ML guidance

1. Anticipate means of compliance for Learning Assurance objectives

on ML Model guarantees (generalization and robustness)

→Exploit the Horizon Europe Research project MLEAP on 'Machine LEarning applications APproval'

partnering on research projects is a key driver for the guidance!

2. Operational explainability & human centric aspects of Al

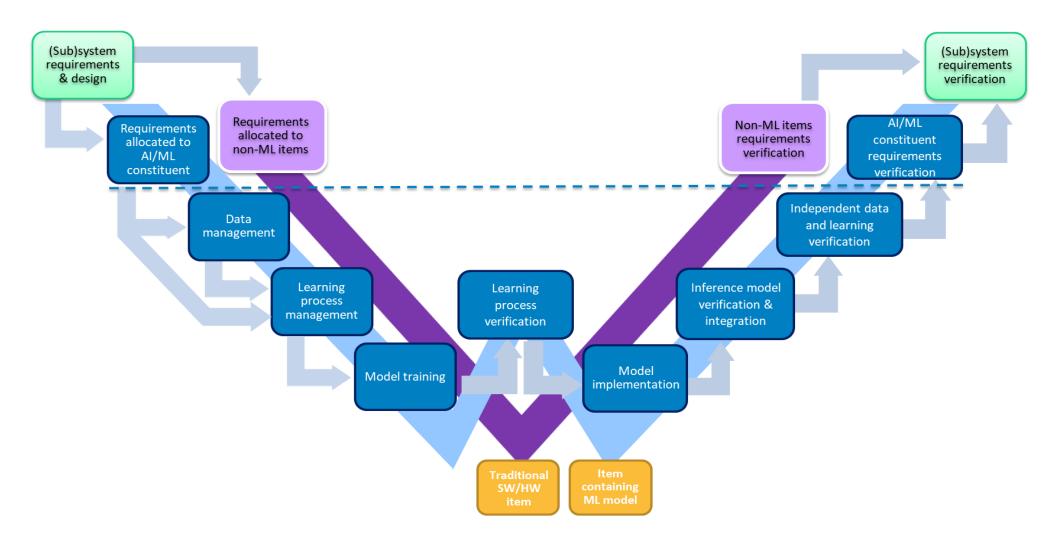
→Foster trust in the human-AI teaming by developing specific Human Factors guidance.

- 3. Ethics-based assessment social & societal aspects
 - →Evaluate and refine guidance based on use cases



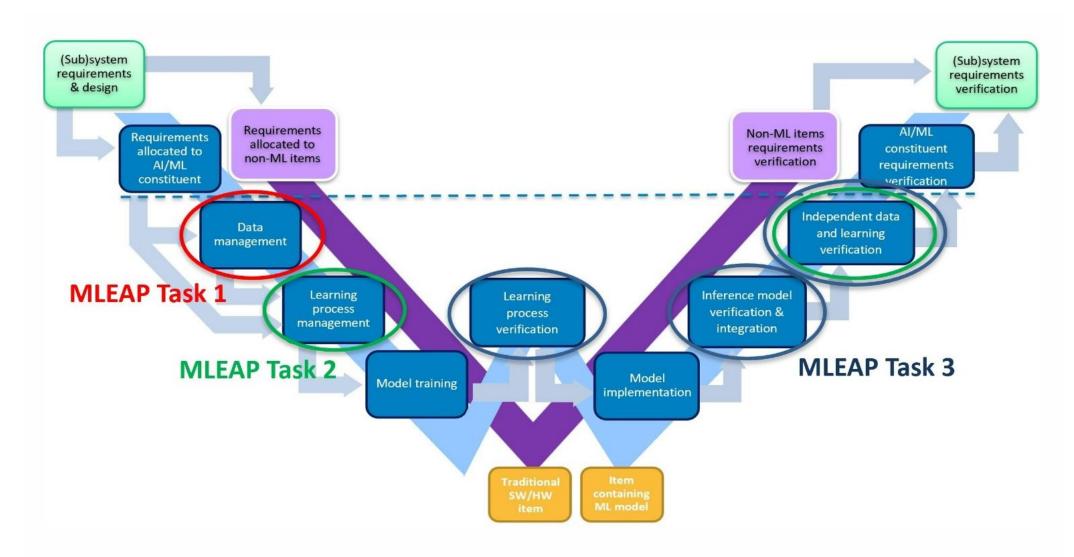


W-shaped assurance process





W-shaped assurance process





Machine Learning Application Approval (MLEAP) project

Objectives

"Streamline certification and approval processes by **identifying concrete means of compliance with** the learning assurance objectives of the **EASA guidance for ML applications**

Budget

1.475 Million Euros funded by EU Horizon Europe

Timeline

May 2022 - May 2024

Research consortium

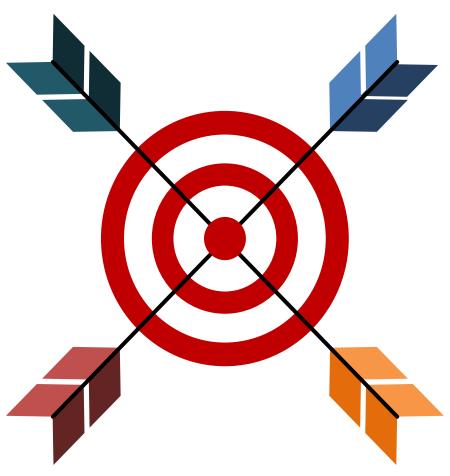
Airbus Protect - LNE - Numalis





What is MLEAP project?

Task #2 Generalization guarantee



Task #3 Algorithm and model robustness

Task #1 Data completeness and representativeness

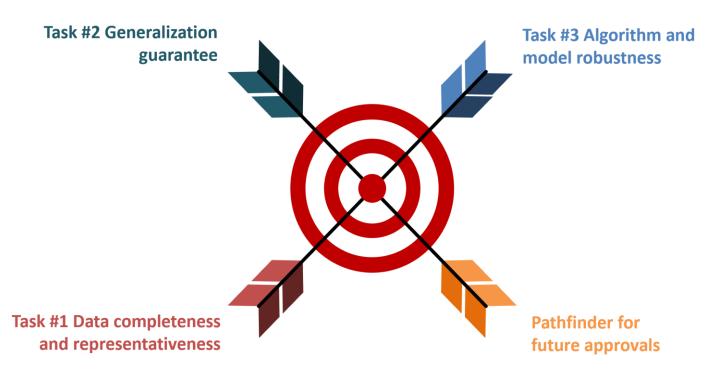
Pathfinder for future approvals



MLEAP Task 1 - Data completeness and representativeness

- Data quality is a challenge due to inherent costs
- Data completeness and representativeness are usually not addressed per se:
 - Almost no dedicated tools
 - Tradeoff between representativity and diversity

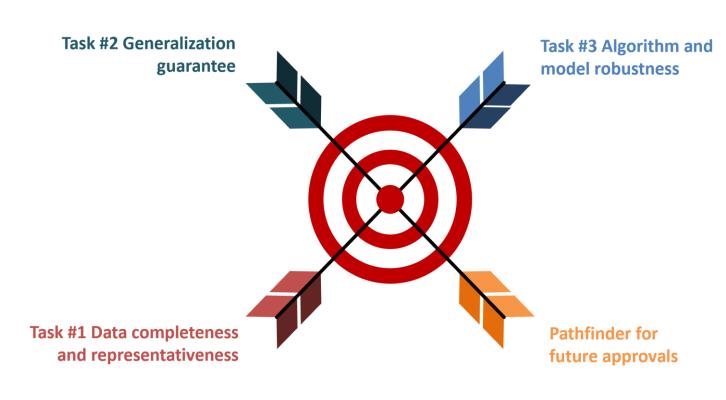
...But crucial to AI/ML performances & guarantees



MLEAP Task 2 - Generalization guarantee

- Ability of AI/ML to scale up to unseen data during training is one of main concern with safety critical applications
- This task aims at defining protocols and strategies to enhance the ability of released models to generalize well

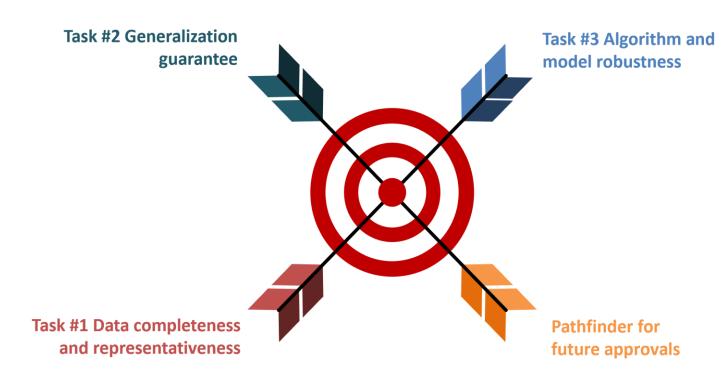
... accounting for data quality and volume and obtaining quantifiable guarantees.





MLEAP Task 3 – Algorithm and model robustness

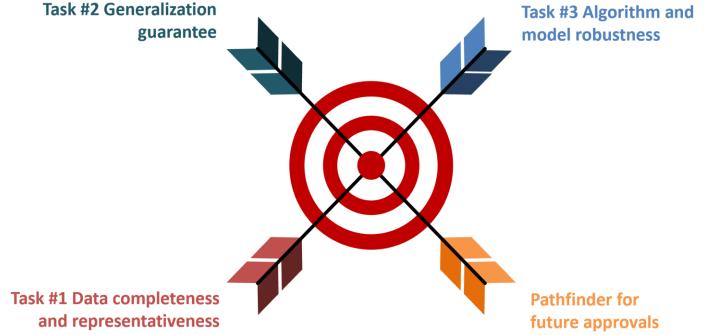
- Aligning existing concepts and definitions between EASA <u>Concept</u> <u>Paper</u>, CoDANN <u>I</u> & <u>II</u> IPCs and ISO/IEC 24029
- Variety of approaches available: Empirical, statistical and formal methods
- Part of the ongoing effort of evaluating formal methods benefits (e.g. EASA-Collins Aeropsace <u>ForMuLA IPC</u>)





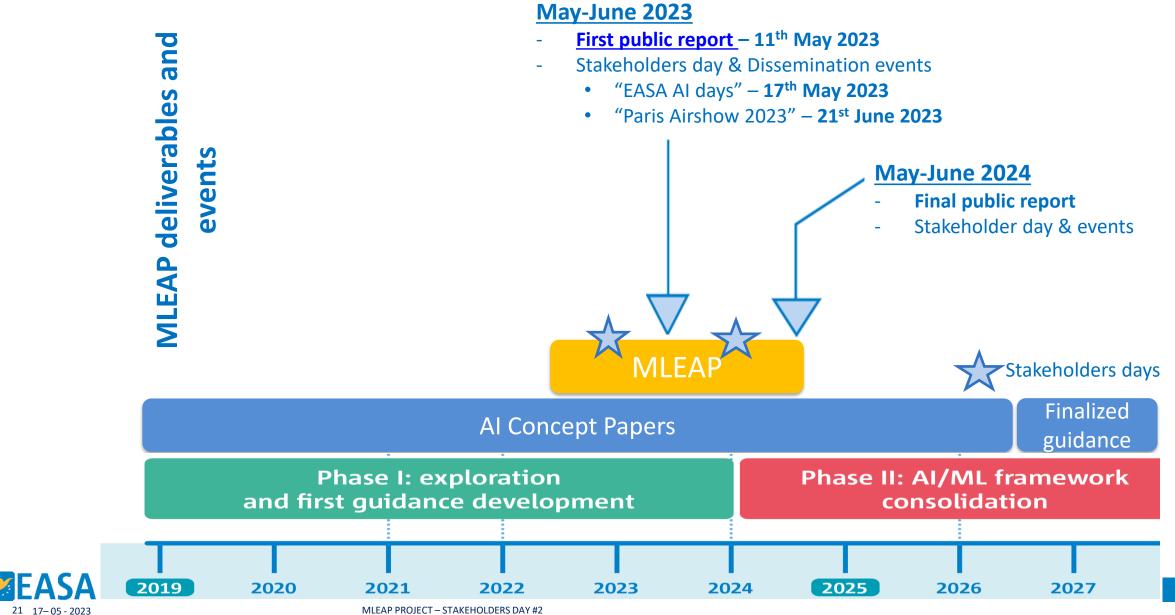
MLEAP - Pathfinder for future approvals

- Practical aviation AI/ML use cases
 - EASA access to detailed models
 & datasets
 - Public data/examples used when possible to allow comparison with 3rd parties
- Knowledge sharing
 - Events organized every 6 months
 - Project <u>page</u> with latest results
 - Public reports
- EASA AI Concept paper regularly updated with MLEAP outputs





MLEAP project milestones



22

MLEAP – Presentation of the Use Cases

Objective:

Lead and support the methods/tools selection process: Data qualification, Models evaluation, and Performance verification

Perform a comparative evaluation, of selected methods and tools, to assess their efficiency

Help making recommendations for possible means of compliance



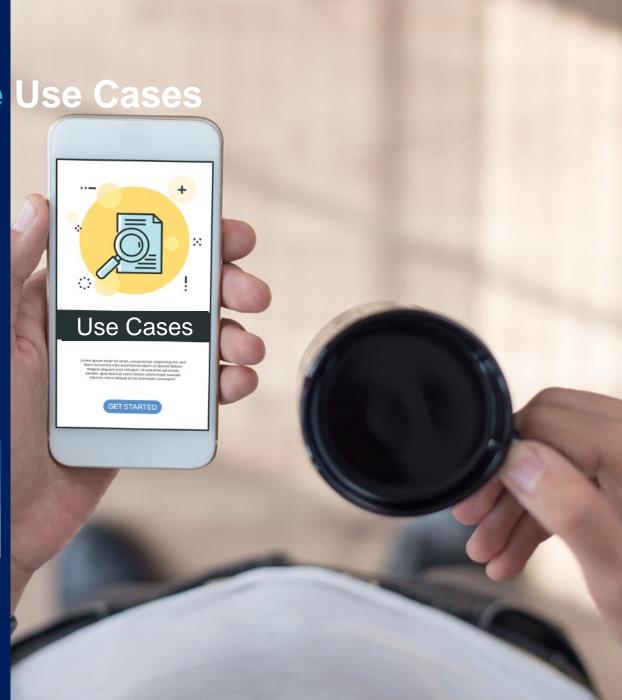
Speech to text STT - ATC



Automated visual inspection AVI



Collision avoidance ACAS - Xu

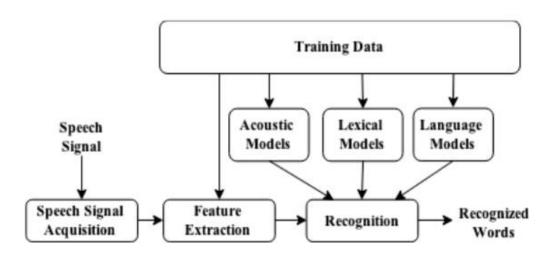


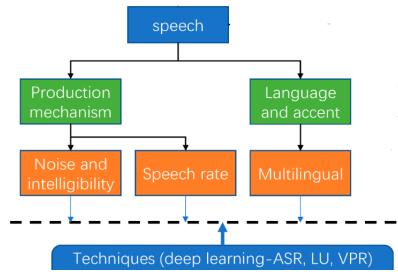
MLEAP – Use Cases Description> > >

Speech-To-Text for Air Traffic Control (ATC-STT)

- ➤ Objective: correctly translate spoken instructions ATCO to text for safer monitoring
 - Language Understanding (LU): (Raju et al., 2021) systems provide both text and semantics associated with every input utterance.
 - Spoken Instruction Understanding (SIU): (Lin, 2021) correctly interpret the ATCO instructions communicated between the control tower and the pilots

VoicePrint Recognition (VPR): (Saquib et al., 2011) or Speaker Recognition Systems (SRS), aim to validate a user's claimed identity
using characteristics extracted from their voices







MLEAP – Use Cases Description> > >

Speech-To-Text for Air Traffic Control (ATC-STT)

➤ Model & Data:

From Airbus internal project & open-source data/models

Data (utterances + transcriptions):

Airbus data: ATC interactions, in English, 100h French accent, 50h Chinese accent

Open Source: real (ATCO2, UWB, NIST LDC-ATC),

simulated (ATCO Sim),

several accents (Chinese, French, German, Slovak,

Australian),

US, ~44h30min

Models (classical and DL-based)

Airbus models: Kaldi STT models implemented with VOSK,

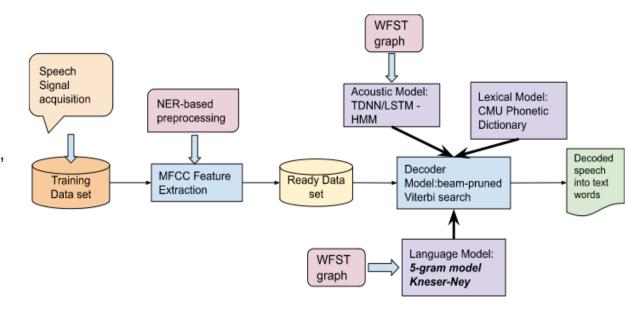
accent/callsign models (DNN classifiers)

Open Source models: DL models,

based on transformers facebook/wav2vec2-

large-960h-iv60-self

MLEAP Challenges: robustness toward noise and different accents, accents detection, Callsign detection





MLEAP – Use Cases Description> > >

Automatic Visual Inspection (AVI)

Objective: « help operators to perform the in-service damage detection, to reduce the aircraft maintenance duration, for scheduled and unscheduled events."

Model & Data: from Airbus internal project & open-source (TBC)

Data: are made of two main parts, lightning strikes and dent impacts, with data augmentation (Changyu et al., 2014);

Acquisition of pictures is done from cameras and downloaded to the design/deployment environment; Labelling is done using the VOTT tool, where every image can contain several damages of different classes;

Weighting samples to cope with imbalanced data sets

Model: is made of Siamese network constructed for a multitasking framework;

Aims to detect both the damage type (dent impact or lightning strike) and its characterization (severity level);

Using openCV library

MLEAP Challenges:

Automatic detection of external damages and their classification into two types: lighting strike impacts and dents:

It is an on-going project, materials (metrics, models and data) are still under development

Find acceptable metrics to bring computer vision models to human abilities on surface damage detection First targeted performance: >95% accuracy correctly detecting damages



Dents Damages (1)



Lightning Strike impacts (2)

- https://www.researchgate.net/figure/Wing-skin-metal-dentexamples_fig3_331961295
- https://www.researchgate.net/figure/Structural-damage-inthe-outer-skin-in-the-Airbus-A400-M-airplane-after-thelightning fig8 305817924



MLEAP – Use Cases Description > > >

Next-Generation <u>Airborne Collision Avoidance System for Unmanned aircrafts (ACAS Xu)</u>

Objective:

ACAS is a universal system-to-system collision avoidance It issues horizontal turn advisories to avoid an intruder aircraft Leverage NNs to solve ACAS problems (Bak and Tran, 2022)

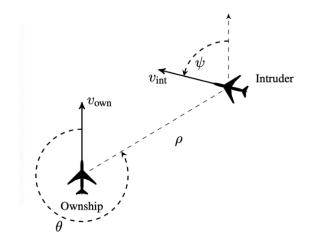
Model & Data:

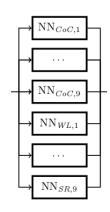
The data consists of different entries of the LUTs from the <u>RTCA SC-147 MOPS</u> The chosen action shall minimize the probability of collision:

- ρ (ft): Distance from ownship to intruder
- \circ θ (rad): Angle to intruder relative to ownship heading
- ο ψ (rad): Heading angle of intruder relative to ownship heading direction
- o vown (ft/s): Speed of ownship
- o vint (ft/s): Speed of intruder
- ο τ (s): Time until loss of vertical separation

MLEAP Challenges:

In a context where the complete ODD is known, data quality is highly dependent on the LUTs Models generalization & robustness are evaluated based on the ability of the model to correctly compress LUTs





ML model elements of the ACAS Xu system



MLEAP Report

First version of the MLEAP deliverable, next and last version in a year.

A nice 260 pages document.



MLEAP – Report – The Topics



Representativeness and Completeness

Corner cases and outliers

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Models

Generalization properties





MLEAP – Report – The common steps

Definitions

What are the meanings of the terms What do the various documents (standards, CP, ...) define What meaning do we choose for the report

Experimentation

How the tools and methods actually behave with various data or models Experiment around scaling Try with aviation use-cases

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State of the Art

Review of scientific littérature Review of existing methods and tools Construction of selection grids to associate use-cases and methods/tools

Projection into the W-shaped process Generalize the methodologies as much as reasonably possible Structure inputs for use by the EASA in their works



MLEAP – Report – The document



MLEAP PROJECT - STAKEHOLDERS DAY #2

Introduction

Use cases

Data: representativeness and completeness

Model development: generalization properties

Model evaluation: robustness and stability

Conclusions



MLEAP – Report – The next steps

Complete the selection grids Apply the methods to the use cases Complete the experimentations Listen to the feedback from all of Consolidate the projection to you the W-shaped process ai@easa.europa.eu

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MLEAP - Task #1 milestones: Data Completeness & Representativeness

Completeness: A data set is complete if it sufficiently covers the entire space of the operational design domain for the intended application.



Representativeness: A data set is representative when the distribution of its key characteristics is similar to the actual input space of the intended application





Task #1 : Data Completeness and Representativeness

Task #1 objectives (so far)

State-of-the-art: Provide a list of factors influencing the choice of tools and approaches in order to assess the completeness and representativeness of databases, with corresponding justifications and bibliographical references.





Task #1 : Data Completeness and Representativeness

Task #1 objectives (so far)

- State-of-the-art: Provide a list of factors influencing the choice of tools and approaches in order to assess the completeness and representativeness of databases, with corresponding justifications and bibliographical references.
- Synthesis: Present a draft structure of the selection grid for the assessment tools and methods.





Task #1 : Data Completeness and Representativeness

Task #1 objectives (so far)

- State-of-the-art: Provide a list of factors influencing the choice of tools and approaches in order to assess the completeness and representativeness of databases, with corresponding justifications and bibliographical references.
- Synthesis: Present a draft structure of the selection grid for the assessment tools and methods.
- Testing: Identification or development of efficient and practicable methods and tools for the assessment of completeness and representativeness of data sets (training, validation and test) in the generic case of datadriven ML.



State-of-the-art: influence factors identified

Technical requirements

- Intended behavior
- Model architecture
- Data dimensionality
- Intended level of autonomy
- Intended level of performance
- Intended level of robustness and resilience
- Intended level of stability

Processes

- Data Management requirements (specs)
- Data Quality improvement (augmentation...)
- Data synthesis
- Data sampling
- Labelling
- Pre-processing

Other DQRs

- Balance
- Relevance
- Diversity (discriminative power)
- Diversity (absence of non representative sampling bias)
- Currentness

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Main take aways of the state-of-the-art

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Assessment of data quality in general lacks maturity in the field of AI:

< 10 works are explicitly considering influence factors in their relationship to Completeness/Representativeness Influence factors and target properties are not studied in a structured way Exhaustive data quality of the data set may be actually hard and challenging to attain

Operations required to enhance data quality attributes may be mutually exclusive (e.g. ensuring relevance can be detrimental to representativeness)

Importance of expert contextual trade-off





Main take aways of the state-of-the-art

In literature, the burden of sorting the wheat from the chaff often still rests on the model.

No "off-the-shelf" method to quantify the relationship between a factor of influence and Completeness/Representativeness.

High-dimensionality challenges rarely addressed.

Adaptability of the methods to high-dimensional data needs to be explored.





Task #1: Data Completeness and Representativeness

6 methods selected

(from 11 identified)

Processes

Data Management requirements (2 methods)

Intended level of robustness and resilience

- Data Quality improvement (3 methods)
- Data synthesis (1 method)

Technical requirements

Intended function Model architecture

Data dimensionality

Intended level of autonomy Intended level of performance

Intended level of stability

- Data sampling (1 method)
- Labelling (2 methods)
- Pre-processing

11 methods selected (from 33 identified)

Other DQRs

- Balance (1 method)
- Relevance
- Diversity (discriminative power)
- Diversity (absence of bias) (1 method)
- Currentness (1 method)

3 methods selected (from 18 identified)



Synthesis: Building the selection grid

80+ sources explored, among which 60+ assessment methods analysed



20 methods selected for testing

Sufficient maturity In line with the project objectives



Testing Phase

PCA

- Test task: Classification
- Associated UC: ACAS-Xu
- Test data sets
 - ACAS-Xu
 - Gas sensor array (external)

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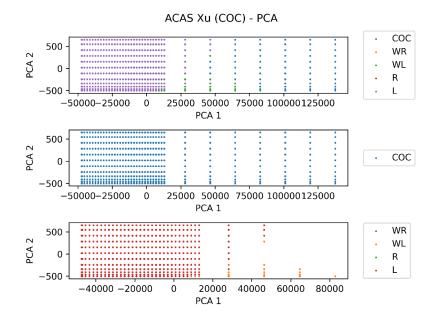
Testing Phase

PCA

- Test task: Classification
- Associated UC: ACAS-Xu
- Test data sets
 - ACAS-Xu
 - Gas sensor array (external)

PCA

- PCA highlighted particularities of the ACAS-Xu dataset
- Triggered further investigations
- Note: ACAS-Xu is probably at the edge of relevance for this method





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Testing Phase

PCA

Entropy (Shannon)

- Test task: Image Segmentation
- Associated UC: AVI
- Test data sets
 - CIFAR-100 (external)
 - ROSE (LNE)





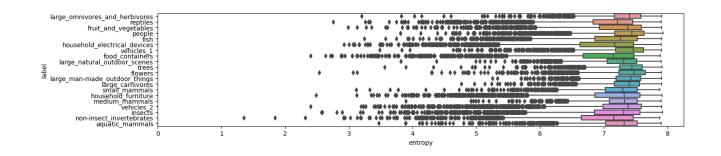
Testing Phase

PCA

Entropy (Shannon)

- Test task: Image Segmentation
- Associated UC: AVI
- Test data sets
 - CIFAR-100 (external)
 - ROSE (LNE)

- Can be used at different level (label-wise, pixelwise...)
- Provides coarse-grain information
- Should preferably be combined with other metrics (yet to be determined)







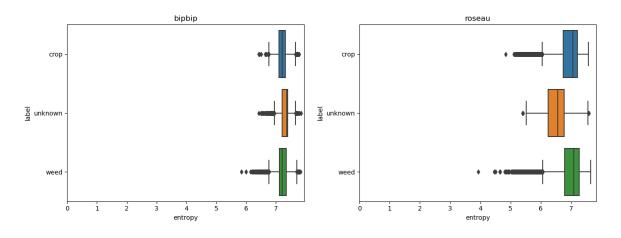
Testing Phase

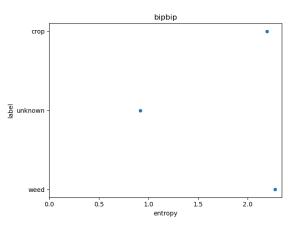
PCA

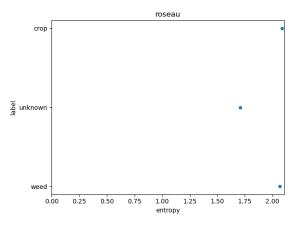
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- Provides coarse-grain information
- Should preferably be combined with other metrics (yet to be determined)











Testing Phase

PCA

Graph (feature combination distribution)

- Test task: Classification
- Associated UC: ACAS-Xu
- Test data set
 - Titanic (external)





Testing Phase

PCA

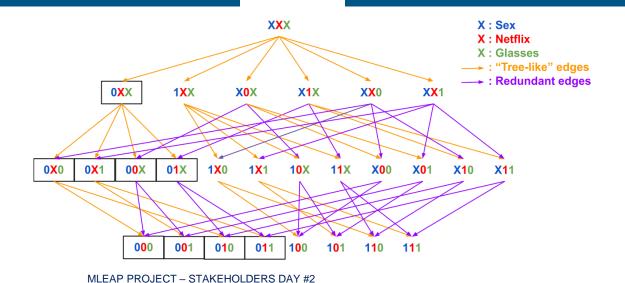
Graph (feature combination distribution)

- Test task: Classification
- Associated UC: ACAS-Xu
- Test data set
 - Titanic (external)

Entropy

Graph

- Results are easy to interpret
- Can be used as an efficient visual tool (like PCA)
- Must be tested at scale







Testing Phase

PCA

Graph (feature combination distribution)

Sample similarity (Degree of Correspondence)

- Test task: Speech recognition
- Associated UC: ATC-STT
- Test data set
 - Fluent Speech Commands (external)





Testing Phase

PCA

Graph (feature combination distribution)

Sample similarity (Degree of **Correspondence**)

- Test task: Speech recognition
- Associated UC: ATC-STT
- Test data set
 - Fluent Speech Commands (external)

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Entropy

Sample similarity

- DoC is inconsistent and intractable on speech embeddings
- This specific method will be put aside
- Similarity-based analysis remains interesting





Main take aways of the testing phase

No method is **self-sufficient**They need to be combined to provide meaningful insight

No method is **universal**The method and their combination must be tailored to each type of task/data



Completeness and representativeness can only be estimated w.r.t ODD specifications

No "absolute measure"

Trade-off between completeness and representativeness for e.g. corner cases





Task #1 : Data Completeness and Representativeness

Next step for Task 1

Adapting identified methods to work on high scale datasets

Continue to test methods of the selection grid

MLEAP – Task #2 Milestones: Model development

State-of-the-art analysis:

Available methods and tools to evaluate generalization bounds;

Barriers in generalization guarantees: ML and DL; Limitation of available methods and common practices;



Identification/selection of suitable methods:

Methods selection; Projection into the W-shaped approach: ML development pipeline;

Experimentation & Evaluation





Supervised machine learning

Objective: Estimate the response y from the data x



What is this animal? y = cat



Training: optimize algorithm parameters to minimize errors on the examples

Machine learning:

- Approximation
- Optimization
- Estimation

Generalization: We are expecting few errors on unseen data. It is based on the assumption that we have regularities behind the data.





MLEAP – Task #2 Milestones : Model development – Generalization

Task #2 : Model generalization

Generalizability

properties > > >

Definition

Model's ability to generalize the learned knowledge to a new context or environment

Success estimator

Statistical tools that estimate how well the model generalizes to unseen data

For $\delta \in (0,1)$ the generalizability of model $\hat{f} \in F$ on w.r.t. data set D is:

$$G(\hat{f}, D) \leq \sqrt{\frac{func(model \ class \ F \ complexity) + \log(1/\delta)}{\|D_{train}\|}}$$

Success indicator

- Evaluation-based: Good performances (w.r.t. some criteria) for Dtest
 Dtrain
- Testing-based: correctness of results during adversarial attacks and spot failure modes

Generalization Guarantees		Algorithm Dependent		
		Yes	No	
Data	Yes	 PAC-Bayesian PAC-Bayesian bounds for NNs (+) more precise, better distributional properties of the learning algorithm 	Rademacher Complexity (RC) RC and regularized Empirical Risk Minimization (ERM) (+) better estimation	
Dependent	No	Model Compression Based on Model Distillation (-) do not take into account data features (+) focuses on the model enhancement	 VC-dimension VC-dimension for NNs (-) Not practical for particular use-cases (Dar et al., 2021) (+) widely applicable 	
	•	Statistical guarantees		





Task #2 : Model generalization

Generalization Bounds

Objective: bounding the deviation of the true risk of the learned hypothesis from its empirical measurement

$$\forall \mathcal{D} \quad \mathbb{P}[|L_D(W) - L_{\mathcal{S}}(W)| \leq \varepsilon(\mathcal{H}, m, \delta, \mathcal{D}, \mathcal{S}, Optim, W)] > 1 - \delta$$

Generalization bound

Several bounds are defined in the littérature based on different theoretical framework, such as:

- Uniform convergence based (Sharpness-based measures)
- Uniform stability based
- Algorithm robustness based
- Mutual information
- Measures related to the optimization procedures

For example: bound based on VC dimension

$$\varepsilon \to \varepsilon(\mathcal{H}, m, \delta) \sim \mathcal{O}\left(\sqrt{\frac{VCdim(\mathcal{H}) + ln(\frac{2}{\delta})}{m}}\right)$$

Algo.	Ref.	Bound
CNN	(Lin and Zhang, 2019)	$R_{\mathcal{D}}(F_C) \leq \hat{R}_{\mathcal{S},l_{\eta}}(F_C) + \mathcal{O}\left(\left(\frac{\ X\ _F \mathcal{R}_C}{\eta}\right)^{\frac{1}{4}} n^{-\frac{5}{8}} + \sqrt{\frac{\ln(1/\delta)}{n}}\right)$
RNN	(Chen et al., 2019)	$R(f_t) \le \hat{R}(f_t) + \tilde{O}\left(\frac{L \times Complexity}{\sqrt{m}} + B\sqrt{\frac{\log(1/\delta)}{m}}\right)$
NN for classification	(P. Jin et al., 2020)	$\mathcal{E}(f) \leq \frac{\sqrt{d} \cdot (1 - \rho_{\tau})}{\min(\delta_0, \kappa \delta_{\tau})} = \alpha(\tau) \cdot CC(\tau)$
NN	(Alquier, 2021)	Catoni's bound (PAC Bayes) $\mathbb{P}_{s}\left(\forall \rho \in \mathcal{P}(\Theta), \mathbb{E}_{\theta \sim \rho}[R(\theta)] \leq \mathbb{E}_{\theta \sim \rho}[r(\theta)] + \frac{\lambda C^{2}}{8\pi} + \frac{KL(\rho \pi + \log \frac{1}{\epsilon})}{\lambda}\right) \geq 1 - \epsilon$
	(Alquier, 2021) (McAllester, 1998)	$\begin{split} \text{Mc Allester's bound} \\ \mathbb{P}_{3}\left(\forall \rho \in \mathcal{P}(\Theta), \mathbb{E}_{\theta \sim p}[R(\Theta)] \leq \mathbb{E}_{\theta \sim p}[r(\Theta)] + \sqrt{\frac{KL(\rho \pi) + \log\frac{1}{\epsilon} + \frac{5}{2}\log(n) + 8}{2n - 1}}\right) \geq 1 - \epsilon \end{split}$

17 bounds selected based on:

- genericity of the bound
- Use cases applicability





MLEAP – Task #2 Milestones : Model development – Generalization

Task #2 : Model generalization

properties >>>

Al issues: from problem analysis to model release



Modeling, Training, Evaluation/Testing, Adjusting, re-training, validating, preparing for release (embedding), behavior analysis ...



Good model

Misunderstanding of the generalization bounds

- Some norm-based measures negatively correlate with generalization
- Conventional bounds based on uniform convergence or uniform stability are inadequate for over-parameterized models

Common mistakes and pitfalls in practice

- Inappropriate training objective
- Inappropriate data representation, volume, split (train, test, valid), quality (noisy, high sparsity)
- Inappropriate model complexity to perform the task, and evaluation metrics

Gap between expectations from evaluation vs the real-world application

- How far away the empirical assessment reflects the reality about the model efficiency?
- Appropriate performance indicators to the application domain cannot ALWAYS be translated by existing evaluation metrics
- How to define a good model? what constitutes a good AI/ML model?
- What about the uncertainty tolerance: how a 85% accuracy is good? how the 15% uncertainty is tolerable?
- How the final model will behave in the target system/environment?

Unhandled ML/DL testing limitation and challenges

- How to define exhaustively the testing scenarios? How to deal with "black boxes in DL"?





Towards application independent ML development pipeline to promote generalizability

Objectives

Deal with models overfitting/underfitting in industry

- Regularization techniques, training adaptation (warm-up and fine-tuning)
- Model/Network architecture and complexity adequacy with the target task

Bridge the gap between experimentation and industrial expectation

- Adopt a multicriteria/additional validation phases;
- Include KPIs (industrial target performance) in the learning objectives and the evaluation metrics as well
- Leverage ML testing properties to promote the quality assurance and help to identify defects and flaws

Better handle the OOD samples and reduce the impact on the safety of the AI system

Deal with rare cases with high impact on the confidence of the model, in order to minimize the risks.

Build an enhanced data and model development pipelines reducing the impact of common practices and pitfalls that result in a weak generalization ability of an ML/DL model, after release/implementation





generalization

MLEAP – Task #2 Milestones : Model development – Generalization properties > > >

Target application definition

$$D \xrightarrow{T_f} (X, Y)$$
, with $T_f(d) = (x, y)$, and $x \in X$ and $y \in Y$

$$T = \begin{cases} f \in F, & (1) \\ X : x_{i} = [x_{i}^{0}, ..., x_{i}^{n}], & (2) \\ Y : y_{j} = [y_{j}^{0}, ..., y_{j}^{m}], & (3) \\ f : X \xrightarrow{f(x)} Y, & (4) \\ M = \{m_{1}, ..., m_{k}\}, & (5) \\ B = \{b_{1}, ..., b_{l}\}, & (6) \\ b_{t}(m_{t} \circ f(x_{t})) \in \{0, 1\} & (7) \\ E = \{e_{1}, ..., e_{z}; (e_{i} \odot x_{i}) = x'_{i}\} (8) \end{cases}$$

- 1) The selected model
- 2) The input space
- 3) The output space
- 4) The mapping function
- 5) Set of SMART objectives & metrics to evaluate their achievements
- 6) Verification scheme and target performances validity/acceptance indicators
- 7) Benchmarking of the model w.r.t (6)
- 8) Elements and/or conditions that directly impact the inputs, and hence the outputs after implementation.

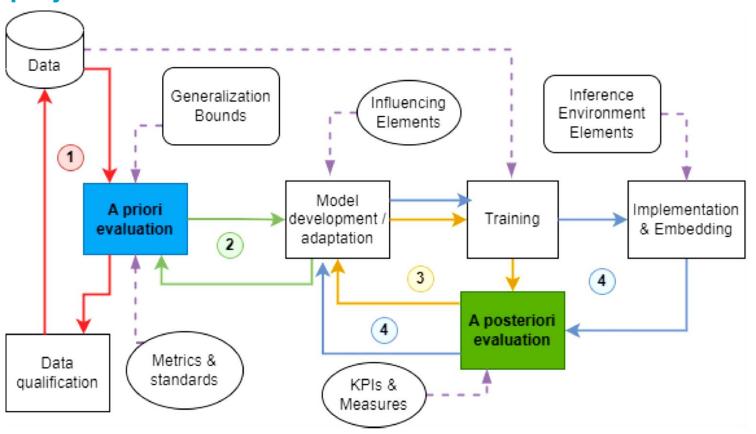




Task #2 : Model generalization

ML Pipeline / W-shaped process projection

- (1) Data evaluation and qualification
 (<=> Task#1)
 - Minimal size of data set needed
 - b. Data quality evaluation (completeness, representativeness)
 - c. Enhancement operations: data augmentation, processing, cleansing, balancing, and splitting;







MLEAP – Task #2 Milestones : Model development – Generalization

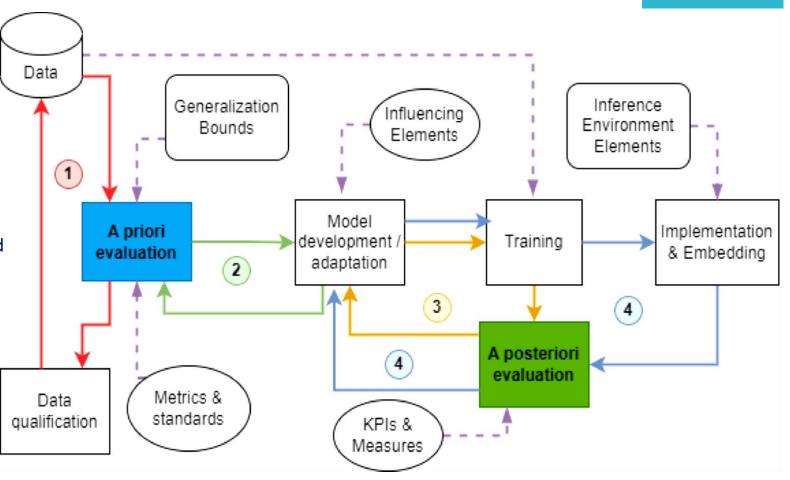
Task #2 : Model generalization

properties >>>

ML Pipeline:

(2) Model development and adaptation

- a. Data Constraints: data size and type, alignment, balance ...
- b. The mappings between the inputs and outputs
- c. Generalization bounds estimation;







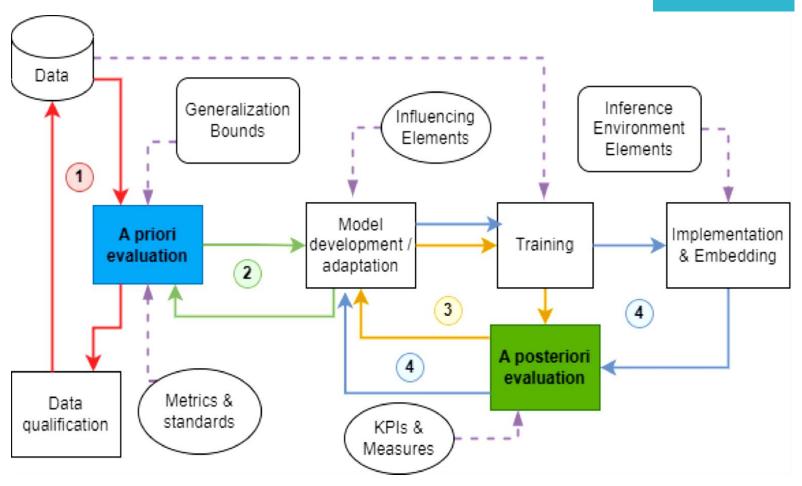
MLEAP – Task #2 Milestones : Model development – Generalization

Task #2 : Model generalization

properties > > >

ML Pipeline:

- (3) Model training on the optimized data set (<=> Task#3)
 - a. Benchmark including a set of industrial KPIs
 - Adapted evaluation measures/metrics/thresholds
 - c. A posteriori evaluation of the trained model: generalization & robustness
 - Measures and loss functions should be adapted to meet the target application objectives





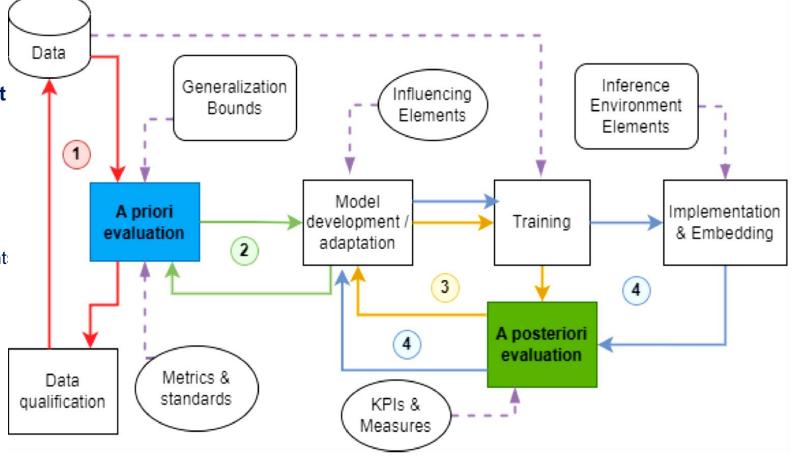


Task #2 : Model generalization

ML Pipeline:

(4) Performance verification in the target environment

- a. Verify the performances after implementation
- b. Different environment and system elements impacting performances
- c. System/target performance requirement are involved
- d. Possible step-back if important drop in performances





Task #2 : Model generalization

Evaluation Objectives

- Analysis of the development pipelines to identify the limitations;
- 2. Analysis of the data quality & volume w.r.t. target performance;
- 3. Analysis of the evaluation schemes: metrics, KPIs, training objectives ...;
- 4. Compare the estimated generalizability VS the real performances;
- 5. Make suggestions: metrics, data OPs, methods to improve existing results and pipelines;
- 6. Validate the suggestions on real-life use-cases.

Experimentation: ATC-STT Task – Models evaluation

Datasets:

- AIRBUS dataset (real ATC exchange from French airports)
 - Open-source datasets (from European airports)

Models:

- AIRBUS model, based on the <u>Vosk API</u> & <u>Kaldi</u> (no Deep Learning), trained on AIRBUS dataset (FR accent included)
- Open-source DL models, based on a transformers architecture, trained on the open-source datasets, fine-tuned in AIRBUS data

Evaluation metric:

- Word Error Rate (WER) = $\frac{S+D+I}{N}$
 - S is the number of substitutions
 - D is the number of deletions
 - *I* is the number of insertions
- N is the total number of words in the reference



Experimentation: ATC-STT Task – Performance Comparison

AIRBUS Vosk Model vs DL Open-source

Excellent performances of the AIRBUS model on the AIRBUS data set and **poor** performances on open-source data sets

Possible bias:

- → Source of data (from a few French airports)
- → Audio quality (noise, microphone used,...)
- → Model architecture and implementation (Vosk API & Kaldi)

Open-source models are trained on larger data sets, and their complexity is more important, but performance on AIRBUS data are average. High-performance on open-source data, regardless of the recording context (accent, noise, etc.) and therefore more robust

Transfer Learning

- →Zero-shot evaluation
- →Fine-tuning on the AIRBUS data

Data Models		AIRBUS data set	ATCO2	ATCOSIM	UWB
AIRBUS Model Vosk		11.50%	91.05%	95.05%	63.46%
Zero- shot	Jzuluaga/wav2vec2 -large-960h-lv60- self-1	34.63%	36.27%	6.82%	20.46%
	Jzuluaga/wav2vec2 -large-960h-lv60- self-2	34.89%	37.14%	22.98%	19.69%
Fine- tuned	Jzuluaga/wav2vec2 -large-960h-lv60- self-1	15.13%	35.81%	15.85%	30.96%
	Jzuluaga/wav2vec2 -large-960h-lv60- self-2	In progress			

Zero-shot evaluation results showing averaged WER of the models



Means that the model is trained in the Dtrain part of the data set

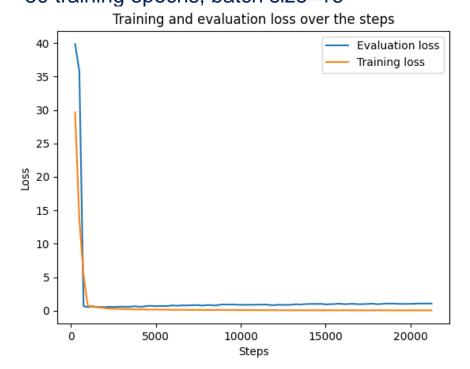


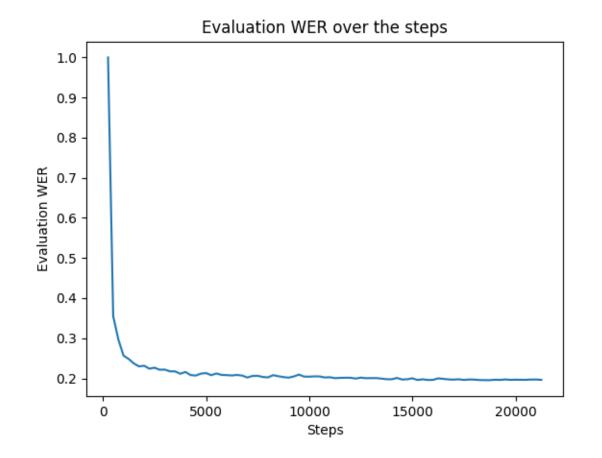


Experimentation: ATC-STT Task – Performance Comparison

Fine-tuning configuration:

AIRBUS data set: 6 826 utterances (~5h11) 50 training epochs, batch size=16









Task #2 : Model generalization

Next step for Task 2

Experimentation and Evaluation:

General framework development and tests of identified bounds and methods

Review of methods and tools

Review of methods to identify corner cases and abnormal inputs

Identification of sources of instabilities during the design phase

Identification of sources of instabilities during the operational phase

Demonstration on a use-case for the intended application





Task #3 : Algorithm and model robustness

MLEAP – Task #3 Milestones: Algorithm and model robustness> > >

Why talking about robustness?



One of the key requirement from the HLEG



One of the key objective in the Al Act



Because it is one of the key issue with Al!





Task #3 : Algorithm and model robustness

Why talking about robustness?

Robustness means keeping the performances on the domain of ODD ODD in an open world can be challenging









Nominal case

Variation of nominal case

Adversarial case

A non-existent case

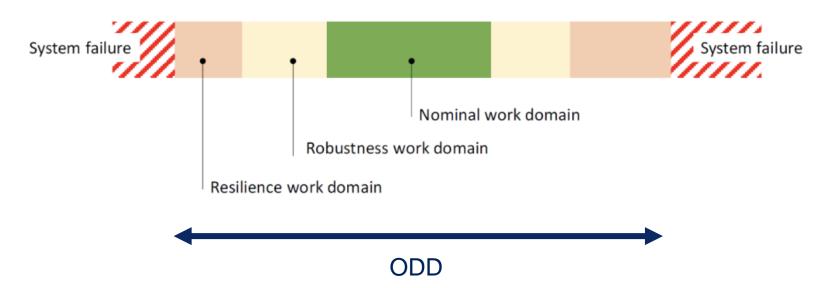




Robustness assessment approaches

Task #3 : Algorithm and model robustness

How to ensure that the system still works when it should? Three types of approaches: statistical, formal, empirical







Task #3 : Algorithm and model robustness

Different ways of defining the concept

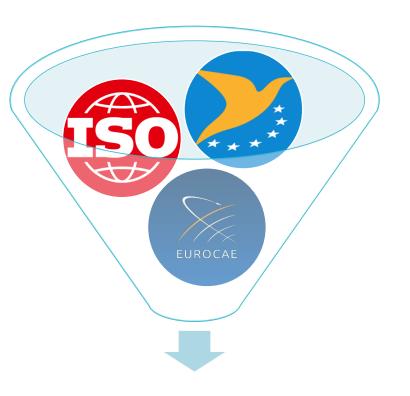
Aligning several sources of the state of the art

- Different concepts robustness, stability, corner cases...
- Different requirements
- Different methods: statistical, formal, empirical

Studying the maturity of the ecosystem

- Scalability of the methods
- Applicability to the relevant use-cases

Preparing the application on the use case



Harmonized state of the art





Common properties to assess

Task #3 : Algorithm
and model robustness

Stability (of the training algorithm, trained model and inference model)	$ x' - x < \delta \Rightarrow \hat{f}(x') - \hat{f}(x) < \varepsilon$		
Bias (~ underfitting)	$bias^{2}(\mathcal{F},n) = \mathbb{E}_{x \sim \mathcal{X}} \left[(\overline{f_{n}}(x) - f(x))^{2} \right]$		
Variance (~ overfitting)	$var(\mathcal{F}, n, x) = \mathbb{E}_{D \sim \mathcal{X}^n} \left[\left(\hat{f}^{(D)} - \overline{f_n}(x) \right)^2 \right]$		
Relevance (~ explainability)	Acceptability of contribution of each dimension of the input vector		
Reachability	$\mathcal{E}^n\left(x,\hat{f}^n(x)\right)\notin Z$		



Task #3 : Algorithm and model robustness

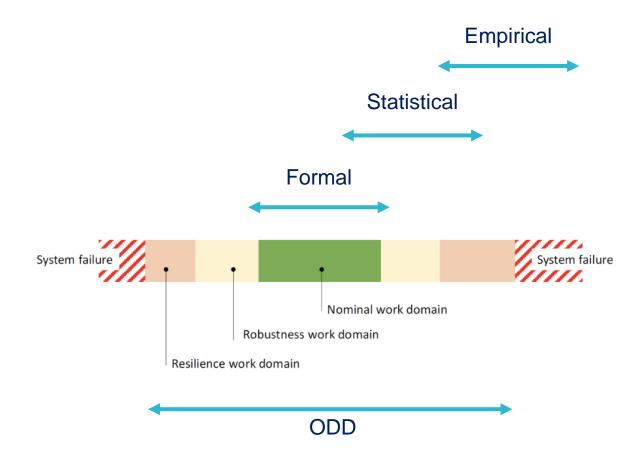
Complementarity of methods

Conceptual alignment is possible

- Stability around the nominal conditions
- Robustness to more difficult conditions
- Resilience to adverse conditions

Methods are complementary

- Depends on the ODD description
- Combining approaches to match the requirements
- ...but varying degree of scalability



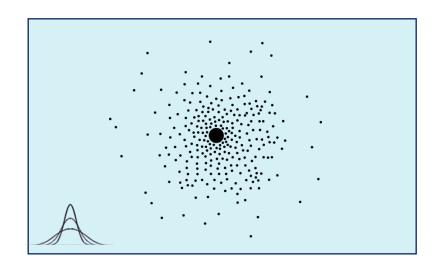




3 approaches at a glance

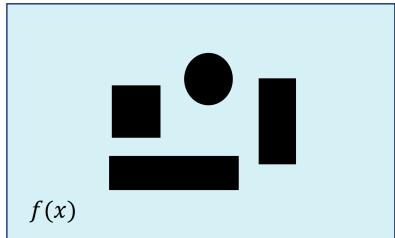
Each allow specific advantages and drawbacks

Statistical



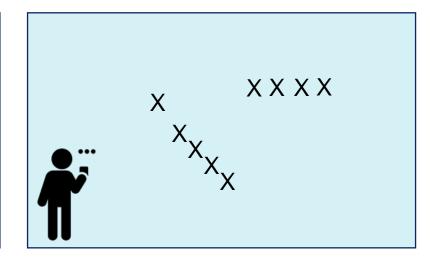
Easy to setup Rely on data sets

Formal



Local guarantees
High dimensional sub-space

Empirical



Require human intervention Experimental protocol



Task #3 : Algorithm and model robustness

Corner case exploration

Different ways of exploring of the ODD

Different level to define corner case in the ODD (context: automotive)

- Scenario (several instants)
- Scene (one instant)
- Objects
- Domain (weather)
- Pixel (camera)



(From Heidecker et al., 2021)



Task #3 : Algorithm and model robustness

A priori assessment of suitability

	Empirical methods	Statistical methods	Formal methods
Stability of the training algorithm			
Stability of the trained model			
Stability of the inference model			
Bias			
Variance			
Relevance			
Reachability			
Corner case exploration			

Scalability	Human intervention needed	Doable but through sampling	Doable but locally
Methods	Field trialA posterioriBenchmarking	Combining metrics	SolverAbstract interpretationOptimization





Task #3 : Algorithm and model robustness

Next step for Task 3

Applying a panel of suitable approaches on the different use cases to exemplify the guidance



Project?

Airbus Protect / Artificial Intelligence Days At Paris Air Show June 21st >>

June 21st:

Awareness session conference:

from 10 to 11am at Airbus Pavillon - On Invitation only

Knowledge Sharing Conference & Networking:

from 3 to 5pm - at VIPARIS Conference center - Conference Room N°2 -

LEAP

numalís

Our partners:





WHAT's next for MLEAP?

PROJECT:

MLEAP Final report in 1 year from today

EVENTS:

January 2024: MLEAP Stakeholders day #3

Awareness session conference #2

April 2024: Knowledge sharing conference #2

May 2024: MLEAP Stakeholders day #4

STAY INFORMED AND FOLLOW US!



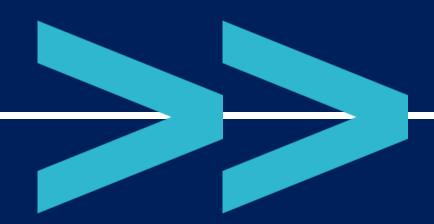
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https://www.protect.airbus.com/

https://numalis.com/

https://www.easa.europa.eu/en/research-projects/machine-learning-application-approval https://events.airbus.com/airbus-protect-easa-paris-air-show/

{Thank you}



NETWORKING LUNCH!

Let's keep the party going!

MLEAP PROJECT - STAKEHOLDERS DAY #2



Thank you for your participation!

Let's continue the discussion until 14:00

around a lunch sponsored by

AIRBUS

PROTECT

Any question?
Please contact us

Please contact us: ai@easa.europa.eu



